Model	Number
5302	D-01A

## TORKDISC® ROTARY TORQUE SENSING SYSTEM

Revision: B ECN #: 44198

Douformones	ENGLISH	SI		1
Performance Measurement Penga (Full Scale Conseits)	2000 in-lb	226 Nm		
Measurement Range(Full Scale Capacity)			ro1	Optional ve
Accuracy Frequency Range(-3 dB)	± 0.10 % FS 0 to 8500 Hz	± 0.10 % FS	[3]	m
		0 to 8500 Hz	[4][E]	
Filter Type(High Pass)	2-pole Butterworth	2-pole Butterworth	[4][5]	
Filter Type(Low Pass - Anti Alias)	8-pole Elliptical	8-pole Elliptical		
Voltage Output(channel A - AC coupled)	± 10 V	± 10 V		
Voltage Output(channel B - DC coupled)	± 10 V	± 10 V		
Gain(Channel A)	1-16 dB	1-16 dB		
Gain(Channel B)	0.3-1.3 dB	0.3-1.3 dB		NOTES
Digital Output	QSPI	QSPI	[6]	NOTES:
Maximum Load(Axial)	500 lb	2.2 kN	[7][8]	[1]Supplied wit [2]Bolt joint slip
Maximum Load(Lateral)	500 lb	2.2 kN	[7][8]	socket head
Maximum Moment	1500 in-lb	169 Nm	[7][8]	[3]Root sum so
Environmental				[4]Selectable F
Overload Limit(Bolt Joint Slip)	3300 in-lb	373 Nm	[2]	[5]Selectable L
Overload Limit(Failure)	8000 in-lb	904 Nm		[6]Request Ted
Overload Limit(Safe)	6000 in-lb	678 Nm		[7]Extraneous
Temperature Range(Rotor/Stator - Operating)	+32 to +185 °F	0 to +85 °C		may be appl
Temperature Range(Rotor - Compensated)	+70 to +170 °F	+21 to +77 °C		[8]Where comb
Temperature Range(Receiver - Operating)	0 to +122 °F	-17.7 to 50 °C		[9]See PCB De
Temperature Effect on Output(System - within compensated range)	0.002 %FS/°F	0.0036 %FS/°C		
Temperature Effect on Zero Balance(System - within compensated range)	0.002 %FS/°F	0.0036 %FS/°C		
Position Sensitivity(180° rotation of sensor)	≤ 0.1 % FS	≤ 0.1 % FS		
Electrical				
Power Required(50 to 60 Hz)	9 to 18 VDC	9 to 18 VDC	[1]	
Digital Resolution	16 Bit	16 Bit	1.1	
Digital Sample Rate	26.484	26.484		SUPPLIED A
Digital Campio Nato	samples/sec	samples/sec		Model 012AC0
Analog Resolution(based on ±10 V FSO and 16-bit resolution)	0.31 mV	0.31 mV		Model 182-028
Physical				Model M00039
Maximum Speed	15,000 RPM	15.000 RPM		
Permissible Axial Float(rotor to stator)	0.25 in	6.4 mm		
Permissible Radial Float(rotor to stator)	0.25 in	6.4 mm		Entered: AP
Rotating Inertia(without adaptors)	0.056 in-lb/sec2			Date: 5/13/2015
Dynamic Balance	per ISO G 2.5	per ISO G 2.5		Bate: 6/16/2016
Torsional Stiffness	5,800,000 in-	655,312		
	lb/radian	N-m/radian		
Torsional Angle(at Full Scale Capacity)	0.020 °	0.020 °		
Housing Material(Sensor)	Anodized	Anodized		
<u> </u>	Aluminum	Aluminum		
Weight(rotor/sensor)	3.5 lb	1.6 kg		
				@PCB
				PPLB !

## **OPTIONAL VERSIONS**

versions have identical specifications and accessories as listed for the standard model except where noted below. More than one option may be used.

rith universal AC power adaptor.

lip torque is calculated assuming a coefficient of friction (µ) of 0.1 and that grade 8 nd cap screws are used and tightened to 30% of yield.

square of non-linearity, hysteresis, and non repeatability.

High Pass cutoff frequencies of 5, 10, 20, 200 and 500 Hz.

Low Pass cutoff frequencies of 10,000, 5000, 2500, 1200, 625 and 313 Hz.

echnical Note FTQ-STN5 regarding digital output signal.

s load limits reflect the maximum axial load, lateral load, and bending moment that plied singularly without electrical or mechanical damage to the sensor.

nbined extraneous loads are applied, decrease loads proportionally.

Declaration of Conformance PS069 for details.

## ACCESSORIES:

024AT Cable (1) 28A Connector (1) 3978 Power supply (1)

Entered: AP	Engineer: JM	Sales: KWW	Approved: JSD	Spec Number:
Date: 5/13/2015	Date: 5/13/2015	Date: 5/13/2015	Date: 5/13/2015	40425



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All specifications are at room temperature unless otherwise specified.

In the interest of constant product improvement, we reserve the right to change specifications without notice.