



Model EX686B72

Intrinsically-safe, USB-programmable electronic vibration switch, relay output, 0.25 to 5 in/sec pk, 7 to 1k Hz, top exit, terminal block and conduit elbow

Installation and Operating Manual

**For assistance with the operation of this product,
contact the PCB Piezotronics, Inc.**

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Operating Guide with Enclosed Warranty Information

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ECO: **55197**

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Introduction

The 686-Series Smart Vibration Switch is a low-cost electronic vibration switch designed to monitor vibration levels on rotating machinery (ie. fans and cooling towers) and trip an alarm or shut down machinery when a specified vibration limit is exceeded. An onboard accelerometer with precision, microprocessor-controlled electronics ensures reliable operation and accuracy. The switch contains a two-pin MIL connector for easy drop-in replacement of mechanical vibration switches and a reliable solid state relay. Multiple units can be installed in a loop configuration for economical installation and expanded protection of critical machinery. This versatile switch can be used to replace more expensive electronic vibration switches where separate vibration output is not required and to replace troublesome mechanical vibration switches.

Every Smart Switch is factory-programmed. See Page 28 for more information.

General Features

- Fully USB-programmable from any PC (with optional USB Programmer Kit).
- Hermetically-sealed, stainless steel housing for use in corrosive environments.
- Imbedded piezoelectric accelerometer for improved accuracy and frequency response.
- Small footprint and single ¼-28 stud mounting.
- Solid state (AC/DC) relay.
- Universal AC or DC power.
- Magnetically Adjustable Vibration Threshold (MAVT™).
- Connects with industry standard MIL-C-5015 connector or integral cable.
- Programmable features
 - Alarm threshold level
 - Normally Open (NO) or Normally Closed (NC) relay
 - Latching or non-latching relay
 - Delays
 - Power on
 - Startup
 - Operational
 - Residual vibration level
- Intrinsically-safe versions available (EX prefix)
 - CSA

Operating Principles

The Smart Switch operates over just two wires. It installs in series with any load (ie. annunciator, PLC or relay coil). To energize itself, the vibration switch scavenges power from the load's power source. When the alarm threshold is exceeded, the switch is activated and the load's power circuit is completed to facilitate the desired alarm or shutdown.

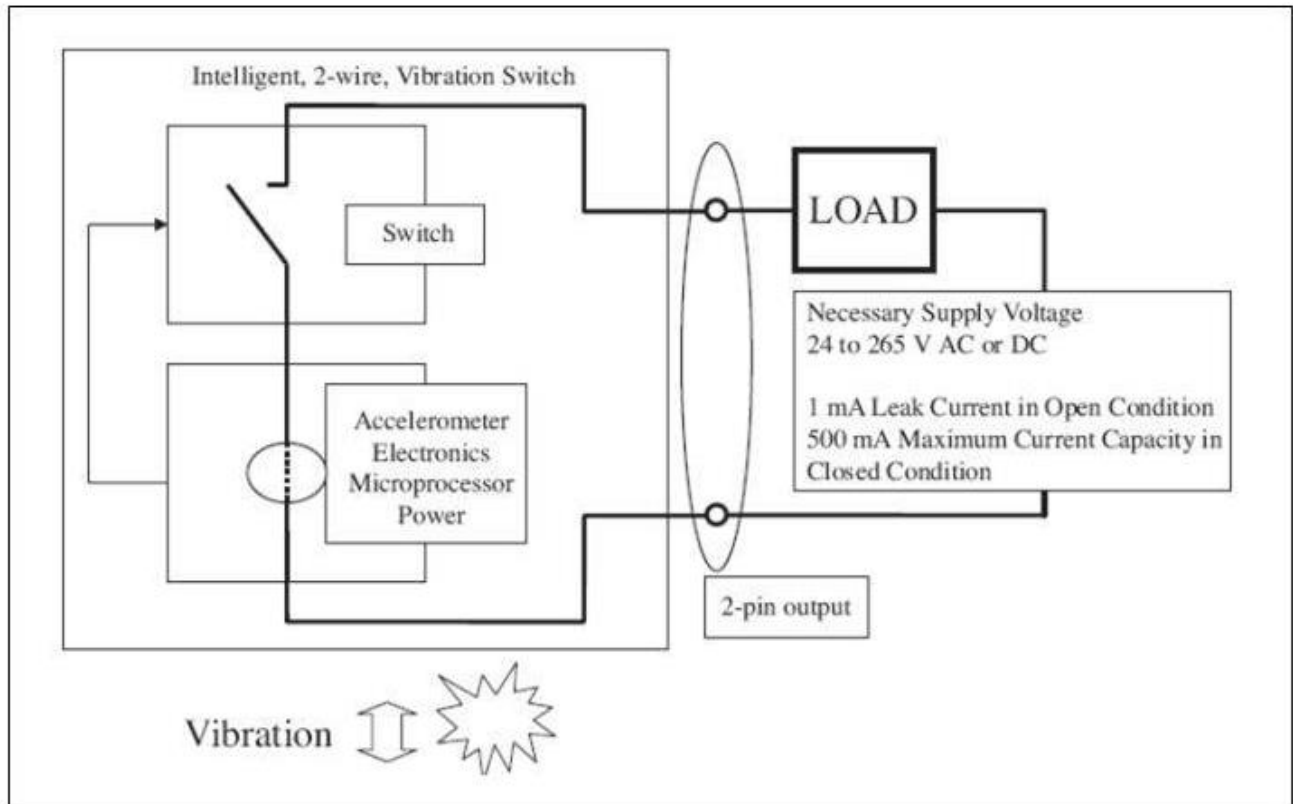


Figure 1 – Block Diagram

Benefits of Solid State Relays

A solid state relay is an electronic component that functions in the same way as an electromechanical relay, but without any moving parts. A solid state relay offers the most reliable switch action, especially for vibration applications where moving relay components run a greater risk of malfunction. They are purely electronic devices composed of a low current control side and a high current load side for switching action.

Installation

When choosing a mounting method, consider closely the advantages and disadvantages of each technique. Typical mounting types are stud, direct adhesive, adhesive mounting base and magnetic mounting base.

Note: For a complete list of product specifications, see the "Specification Sheet" and "Outline Drawing" at the end of this Manual.

Direct Adhesive Mount Procedure

For restrictions of space or for convenience, most sensors (with the exception of integral stud models) can be adhesive-mounted directly to the machine surface.

- Step 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μin (0.0016 mm) generally works best.
- Step 2: Place a small portion of adhesive on the underside of the sensor. Firmly press down on the top of the assembly to displace any adhesive. Be aware that excessive amounts of adhesive can make sensor removal difficult.

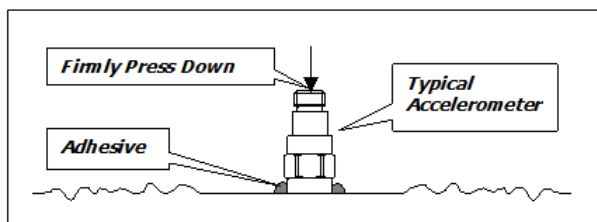


Figure 2 – Direct Adhesive Mounting

Standard Stud Mount Procedure

This mounting technique requires smooth, flat contact surfaces for proper operation and is recommended for permanent and/or secure installations. Stud mounting is also recommended when testing at high frequencies.

Note: Do not attempt mounting on curved, rough or uneven surfaces, as the potential for misalignment and limited contact surface may significantly reduce the sensor's upper operating frequency range.

	1/4-28 Stud	1/4-28 Captive Screw
A (in)	0.250	0.250
B (in)	0.350	0.350
Torque (ft-lb)	2 to 5	2 to 5

- Step 1: First, prepare a smooth, flat mounting surface and then drill and tap a mounting hole in the center of this area. A precision-machined mounting surface with a minimum finish of 63 μ in (0.0016 mm) is recommended. (If it is not possible to properly prepare the machine surface, consider using an adhesive mounting pad as a possible alternative.) Inspect the area, checking that there are no burrs or other foreign particles interfering with the contact surface.
- Step 2: Wipe clean the mounting surface and spread on a light film of grease, oil or similar coupling fluid prior to installation. Adding a coupling fluid improves vibration transmissibility by filling small voids in the mounting surface and increasing the mounting stiffness. For semi-permanent mounting, substitute epoxy or another type of adhesive.
- Step 3: Hand-tighten the sensor/mounting stud to the machine, and then secure the sensor with a torque wrench to the mounting surface by applying the recommended mounting torque (see enclosed specification data sheet for proper mounting torque). It is important to use a torque wrench during this step. Under-torqueing the sensor may not adequately couple the device; over-torqueing may result in stud failure and possibly permanent damage.

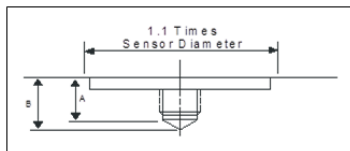


Figure 3 – Mounting Surface Preparation

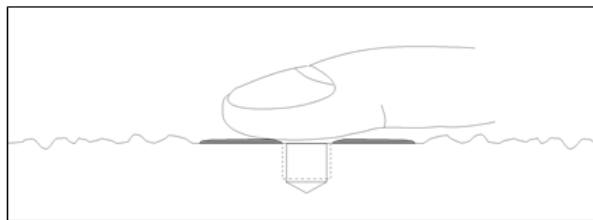


Figure 4 – Mounting Surface Lubrication

Adhesive Stud Mount Procedure

Adhesive mounting is often used for temporary installation or when the machine surface cannot be adequately prepared for stud mounting. Adhesives like hot glue or wax work well for temporary mounts; two-part epoxies and quick-bonding gels provide a more permanent mount.

Note: Adhesively mounted sensors often exhibit a reduction in high-frequency range. Generally, smooth surfaces and stiff adhesives provide the best frequency response. Contact the factory for recommended epoxies.

This method involves attaching a base to the machine surface, then securing the sensor to the base. This allows for easy removal of the accelerometer.

- Step 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.0016 mm) generally works best.
- Step 2: Stud-mount the sensor to the appropriate adhesive mounting base according to the guidelines set forth in Steps 2 and 3 of the Standard Stud Mount Procedure.
- Step 3: Place a small portion of adhesive on the underside of the mounting base. Firmly press down on the assembly to displace any extra adhesive remaining under the base.

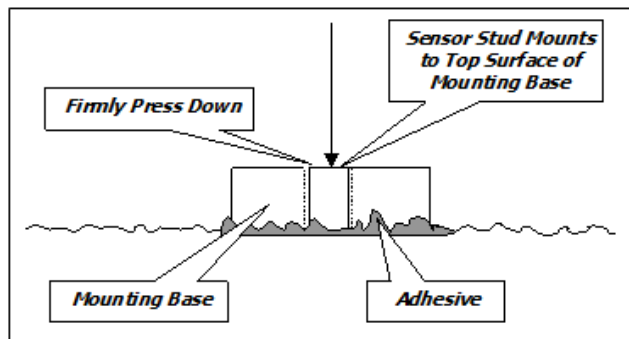


Figure 5 – Adhesive Installation of Mounting Base

Magnetic Mount Procedure

Magnetic mounting provides a convenient means for making portable measurements and is commonly used for machinery monitoring and other portable or trending applications.

Note: The correct magnet choice and an adequately prepared mounting surface are critical for obtaining reliable measurements, especially at high frequencies. Poor installations can cause as much as a 50% drop in the sensor frequency range.

Not every magnet is suitable for all applications. For example, rare earth magnets are commonly used because of their high strength. Flat magnets work well on smooth, flat surfaces, while dual-rail magnets are required for curved surfaces. In the case of non-magnetic or rough surfaces, it is recommended that the user first weld, epoxy or otherwise adhere a steel mounting pad to the test surface. This provides a smooth and repeatable location for mounting.

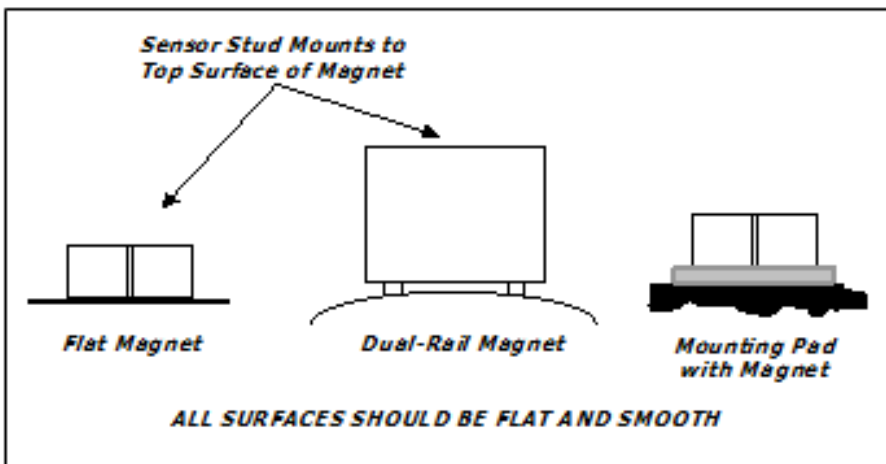


Figure 6 – Magnet Types

- Step 1: After choosing the correct magnet, inspect the unit to verify that the mounting surfaces are flat and smooth.
- Step 2: Stud-mount the accelerometer to the appropriate magnet according to the guidelines set forth in Steps 2 and 3 of the Standard Stud Mount Procedure.
- Step 3: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μin [0.0016 mm] generally works best. After cleaning the surface and checking for burrs, wipe on a light film of silicone grease, machine oil or similar-type coupling fluid.
- Step 4: Mount the magnet/sensor assembly to the prepared test surface by gently “rocking” or “sliding” it into place.

Note: Magnetically mounting accelerometers carelessly has the potential to generate very high (and very damaging) g levels. To prevent damage, install the assembly gently. If unsure, please contact the factory for assistance.

Wiring

On the following pages are eleven different wiring scenarios for the Smart Switch. The wiring legend below is applicable to all wiring diagrams.

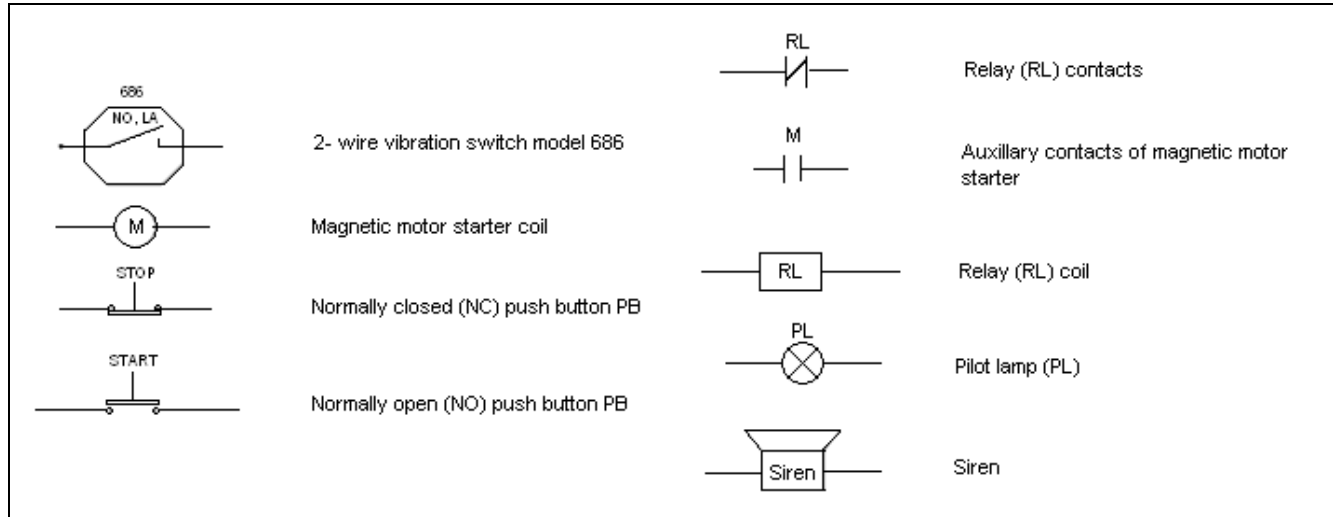
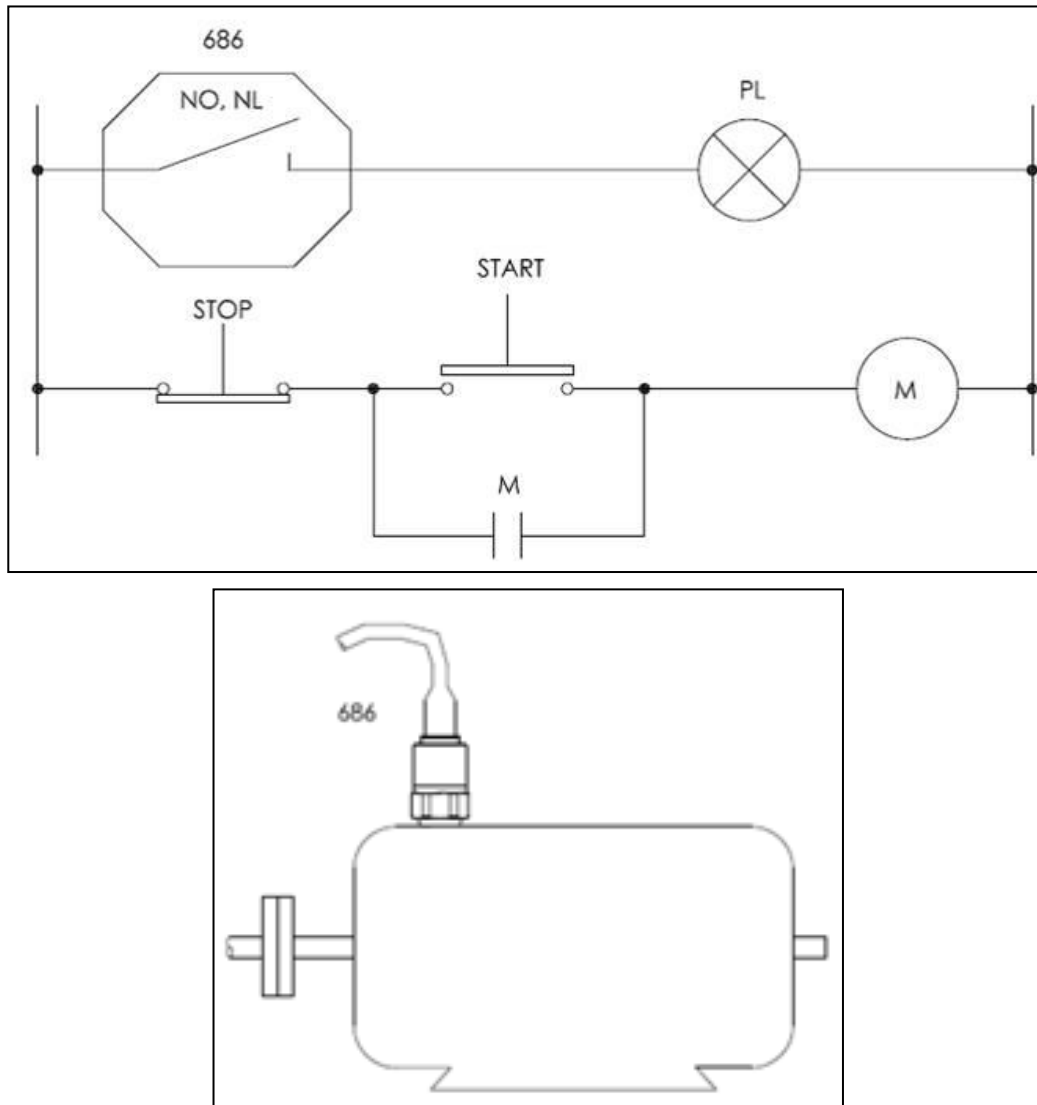


Figure 7 – Wiring Diagrams Legend

For those wiring scenarios that suggest the use of an external electromechanical relay, IMI suggests Omron general purpose relays as listed below. Visit www.omron.com for more information.

Attribute	Omron Model Number				
	MJN2C-AC120	MJN2C-AC240	MJN2C-DC12	MJN2C-DC24	MJN2C-DC110
Contact Form	2 Form C (DPDT)				
Relay Rated Resistive Load	10 A @ 240 VAC/28 VDC				
Service Life- Electrical (Min @Rated Loads)	100,000 operations “average”				
Relay Max Resistive Switching Capacity	2400 VA, 280 W	240 VAC	12 VDC	24 VDC	110 VDC
Coil Nominal Voltage	120 VAC		1.2 W		
Coil Power Consumption	1.7 VA				
Coil Type	Non-Latching				
Seal Type	Unsealed				
Termination Style	Socket Mount				
Operating Temperature Range	-45 to +60 C with no icing or condensation		-45 to +70 C with no icing or condensation		
Dielectric Strength (AC for 1 min)	2500 VAC				
Approved Standards	UL, CSA				

Indicating a High Level of Vibration in a Motor

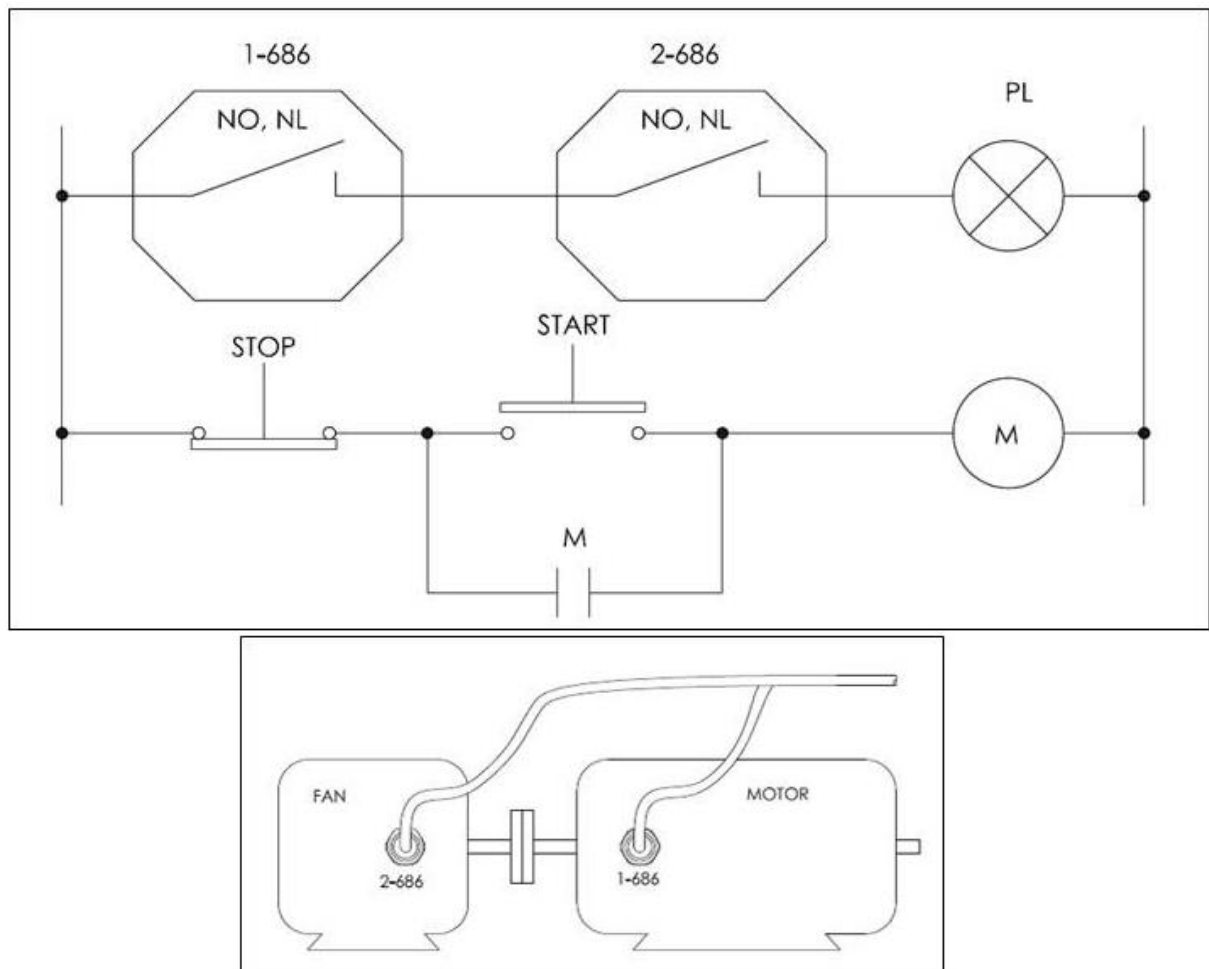


Figures 8 and 9 – Indicating a High Level of Vibration in a Motor

Pushing the Start pushbutton closes the M contacts and starts the motor. If the start-up delay option for the switch is enabled, the Smart Switch will not trip regardless of the vibration level during the specified delay time. After this delay, the vibration switch will be activated. If the vibration level exceeds the alarm threshold for a time period greater than the specified operational delay time, the relay will trip. This action will close the contact to the pilot lamp.

Since the NL (non-latching) option is specified, the pilot lamp will illuminate only while alarm threshold is exceeded. Should the vibration level drop below the alarm threshold value (based also on the specified hysteresis), the pilot lamp will turn off.

Indicating High Levels of Vibration Simultaneously in Series (Such as Fan & Motor)



Figures 10 and 11 – Indicating High Levels of Vibration Simultaneously in Series (Such as Fan & Motor)

The Smart Switches are hooked up in series and installed on the two most loaded bearings across the coupling in the horizontal direction. Pushing the Start pushbutton closes the M contacts and starts the motor and fan. If the start-up delay option for the switches is enabled, the Smart Switches will not trip during the specified startup delay time, regardless of the vibration level. After this delay, the switch relays will be activated if the vibration level on both machines exceeds the alarm threshold for a period greater than the specified operation delay time. This action will close the contact to the pilot lamp.

Since the NL (non-latching) option is specified, the pilot lamp will illuminate only while set threshold on both machines is exceeded. Should the vibration level for one or both of the machines drop below the threshold value (based also on the specified hysteresis), the pilot lamp will turn off.

Constant Siren Alarming in the Event of High Vibration Levels

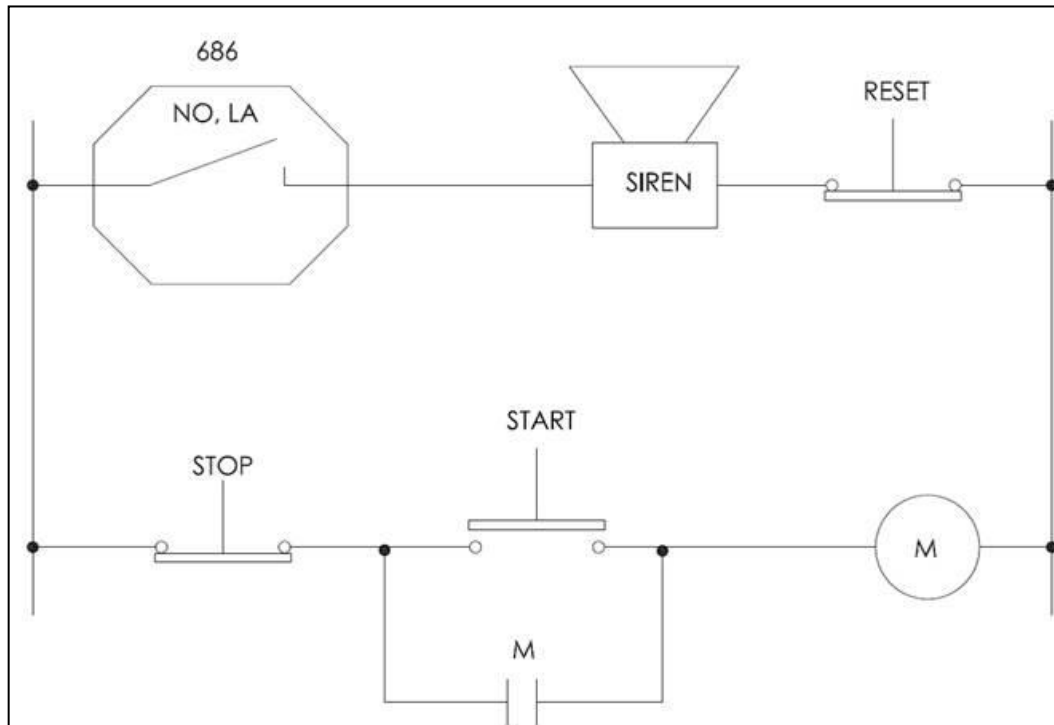
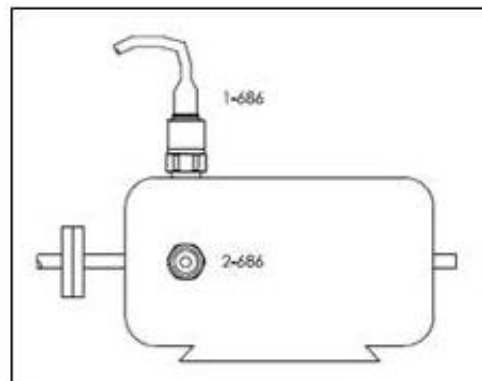
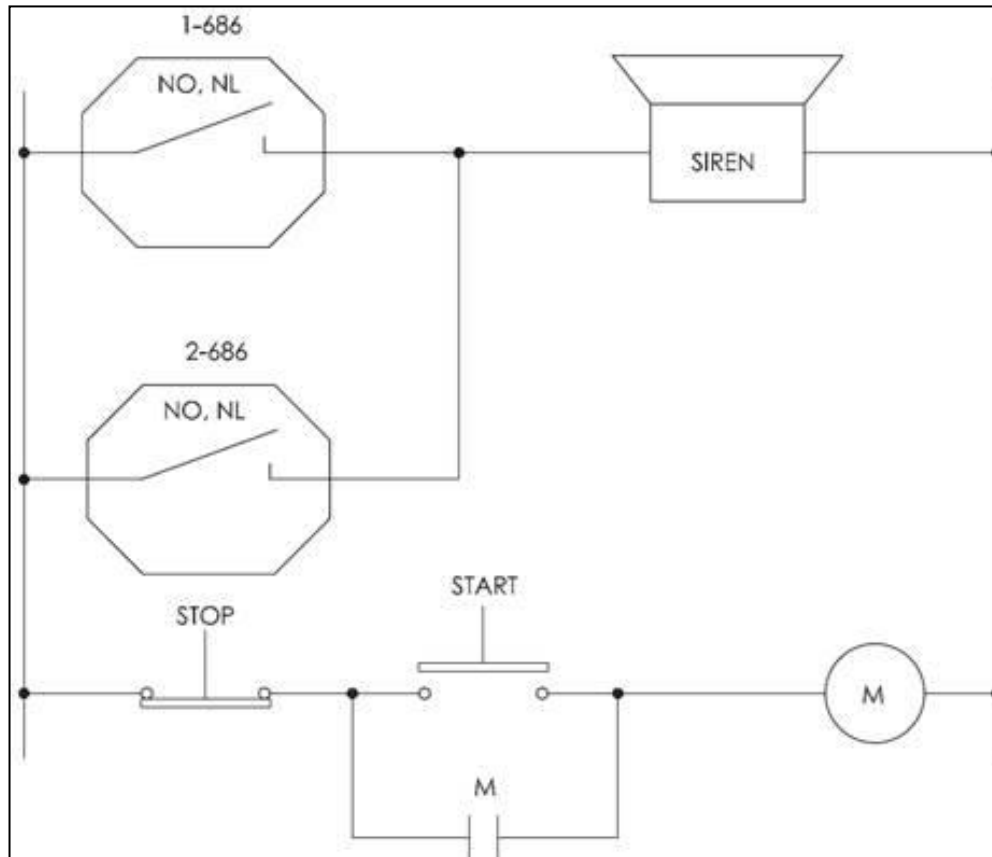


Figure 12 – Constant Siren Alarming in the Event of High Vibration Levels

The Smart Switch is hooked up for automatic constant siren alarming when the alarm threshold level is exceeded. Pushing the Start pushbutton closes the M contact and starts the motor. If the start-up delay option for the switches is enabled, the Smart Switches will not trip during the specified startup delay time, regardless of the vibration level. After this delay, the switch relay will be activated if the vibration level exceeds the alarm threshold for a period greater than the specified operational delay time. This action will close the contact to the alarm siren and activate it.

Since the LA (latching) option is specified, the alarm siren will be constantly energized after this high vibration event, even if the vibration level should drop below the alarm threshold. The Reset pushbutton should be engaged to de-energize the alarm siren and return the system to its original monitoring condition.

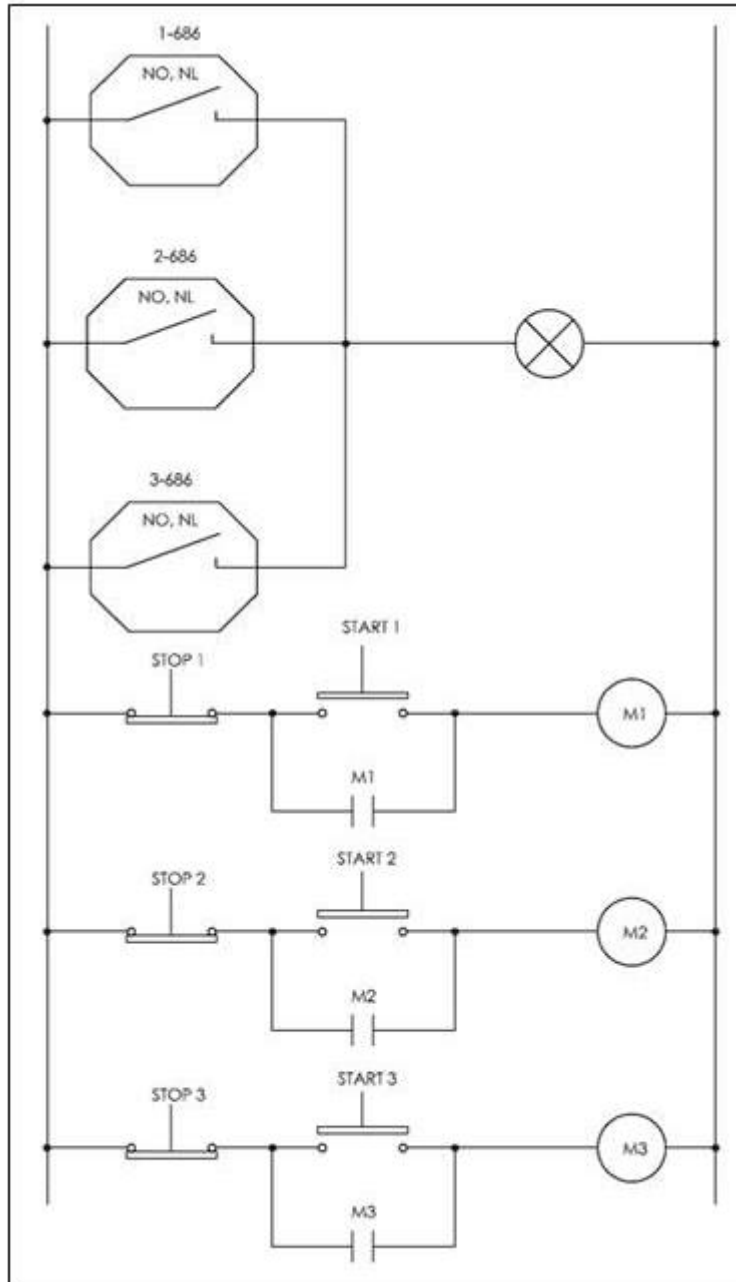
Using Two Switches in Parallel to Monitor Two Axes Simultaneously on Same Motor



Figures 13 and 14 – Using Two Switches in Parallel to Monitor Two Axes Simultaneously on Same Motor

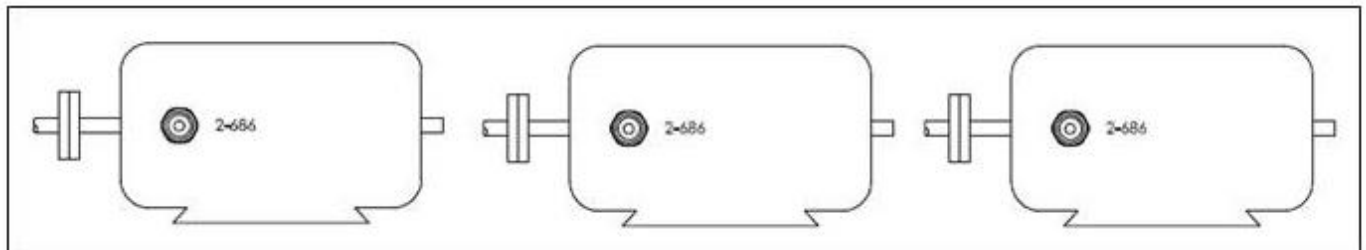
The Smart Switches are hooked up in parallel and installed on the motor in horizontal and vertical directions. Pushing the Start pushbutton closes the M contact and starts the motor. If the start-up delay option for the switches is enabled, then during the specified startup delay time, the switches will not trip regardless of the vibration level. After this delay, the alarm siren will be activated if either of the switches experiences a vibration level over the alarm threshold lasting greater than the specified operation delay time. Since the NL (non-latching) option is specified, the alarm siren will sound while alarm threshold on one or both switches is exceeded. Should the vibration level for both switches drop below the alarm threshold value (based also on the specified hysteresis), the alarm siren will turn off.

Using Three Switches in Parallel to Monitor Three Motors Simultaneously



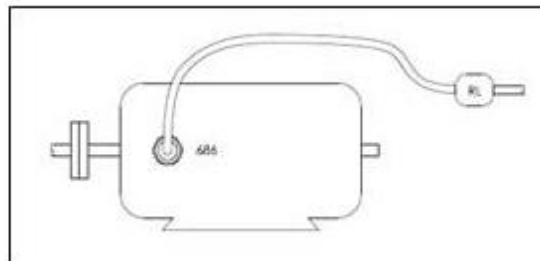
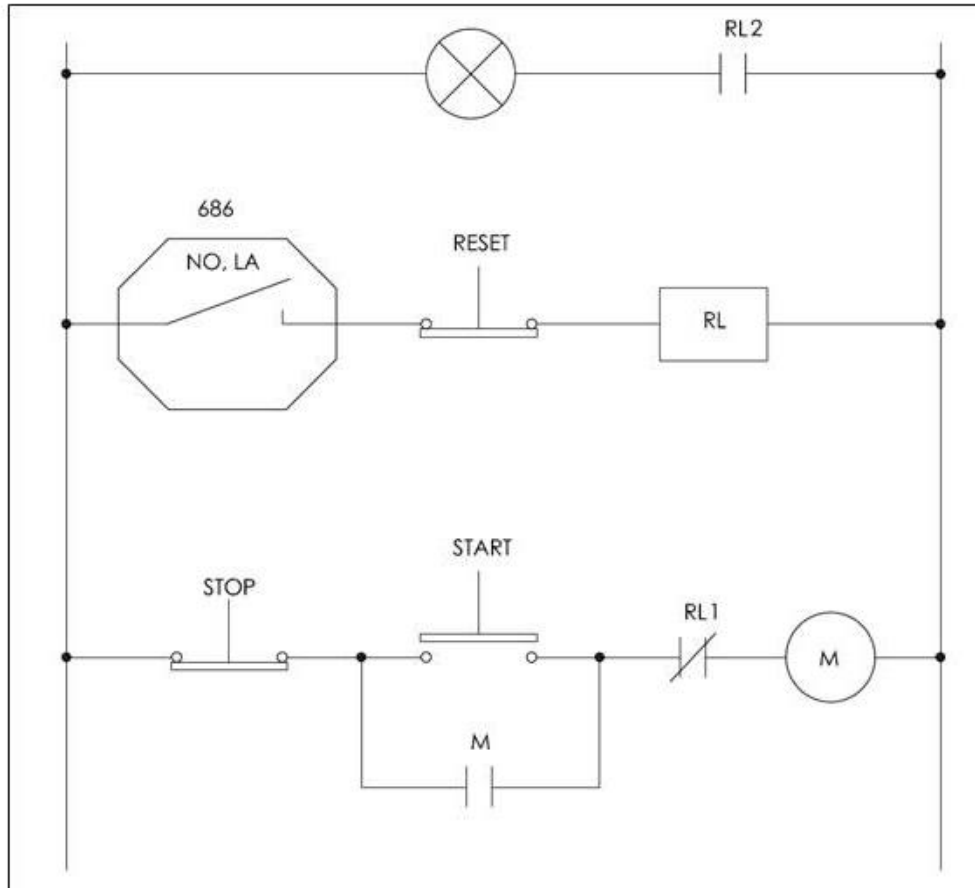
The three Smart Switches are hooked up in parallel and installed on each motor in the horizontal direction. This provides an economical solution for monitoring a group of machinery while only having to run one cable. Pushing any Start pushbutton will close the corresponding M contact and start the motor. If the start-up delay option for the switches is enabled, then during the specified startup delay time, the switches will not trip; regardless of the vibration level. After this delay, the pilot lamp will be illuminated if any of the switches experience a vibration level over the alarm threshold value lasting greater than the specified operational delay time.

Since the NL (non-latching) option is specified, the pilot lamp will illuminate while alarm threshold on any of the switches is exceeded. When the vibration level for all switches drops below their alarm threshold value (based also on the specified hysteresis), the pilot lamp will turn off.



Figures 15 and 16 – Using Three Switches in Parallel to Monitor Three Motors Simultaneously

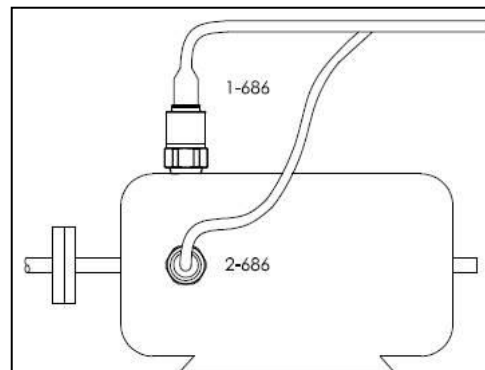
Automatic Machinery Shutdown Using an External Electromechanical Relay



Figures 17 and 18 – Automatic Machinery Shutdown Using an External Electromechanical Relay

The Smart Switch is hooked up for automatic motor shutdown when the alarm threshold level is exceeded. The switch should be mounted in the horizontal direction on the bearing carrying the most load. Pushing the Start pushbutton closes the M contact and starts the motor. If the start-up delay option for the switches is enabled, the Smart Switches will not trip during the specified startup delay time, regardless of the vibration level. After this delay, the switch relay will be activated if the vibration level exceeds the alarm threshold for a period greater than the specified operational delay time. This action will close the contact and send a voltage to the RL relay coil. This will open the RL1 and close the RL2 contacts, shut down the motor, and light the pilot lamp.

Since the LA (latching) option is enabled, the RL coil will be constantly energized after this event; even if the vibration level drops below the alarm threshold value after shutdown. The Reset pushbutton should be pushed to reset the switch and close the RL1 and RL2 contacts before restarting the motor.



The Smart Switches are hooked up in parallel for automatic motor shutdown when the alarm threshold level is exceeded on either switch. The switches should be mounted in the horizontal and vertical direction at the bearing carrying the most load. Pushing the Start pushbutton closes the M contact and starts the motor. If the start-up delay option for the switches is enabled, the Smart Switches will not trip during the specified startup delay time, regardless of the vibration level. After this delay, the switch relay will be activated if the vibration level of either switch exceeds the alarm threshold for a period greater than the specified operational delay time. This action will close the contact and send a voltage to the RL relay coil. This will open the RL contacts and shut down the motor.

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Using the Switch and External Latching for Automatic Machinery Shutdown

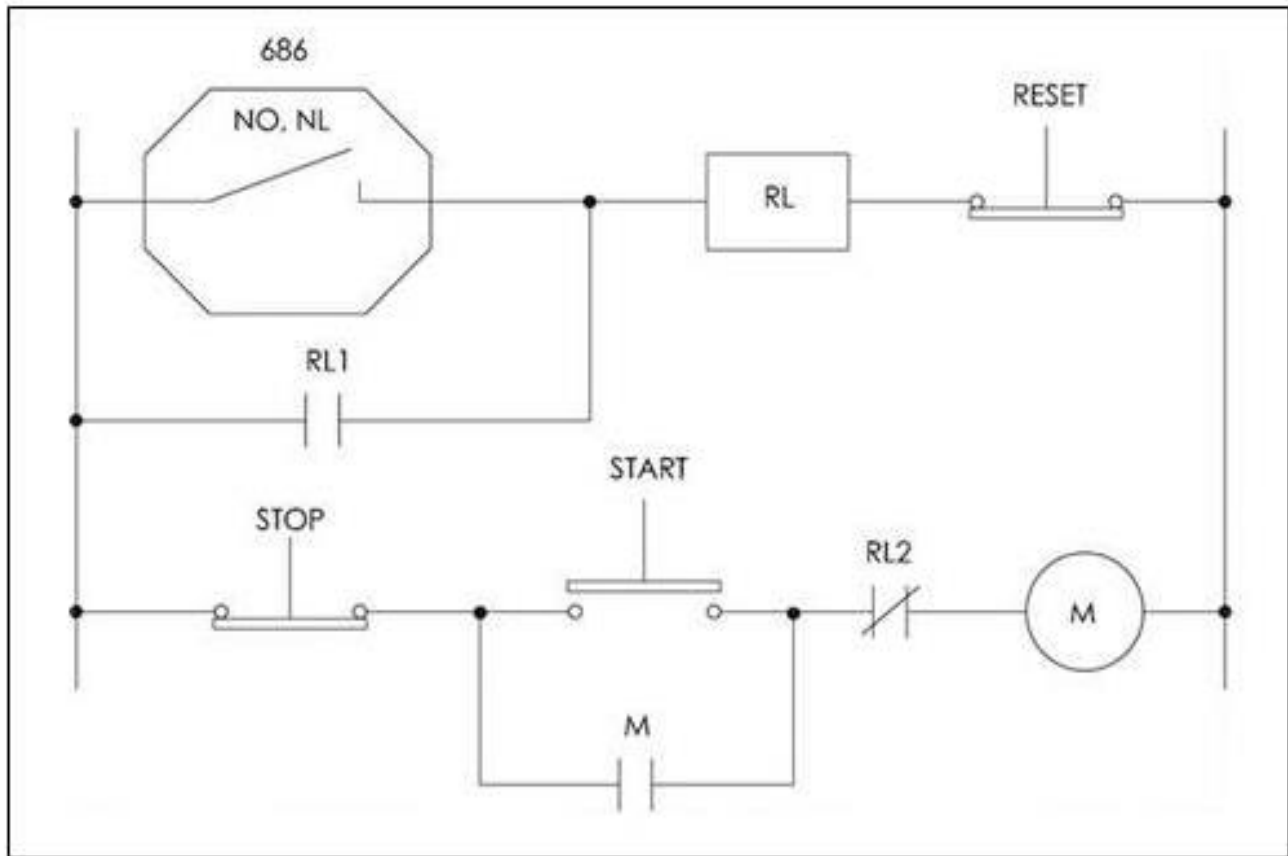


Figure 21 – Using the Switch and External Latching for Automatic Machinery Shutdown

The Smart Switches are hooked up for automatic motor shutdown in case of high vibration levels on critical machinery. Since RL2 contacts are normally closed, pushing the Start pushbutton closes the M contact and starts the motor. If the start-up delay option for the switches is enabled, the Smart Switches will not trip during the specified startup delay time, regardless of the vibration level. After this delay, the switch relay will be activated if the vibration level of either switch exceeds the alarm threshold for a period greater than the specified operational delay time. This action will close the contacts and send a voltage to the RL relay coil. This will open the RL2 contacts and shut down the motor.

Since the LA (latching) option is specified, the RL1 contacts are used for external latching. Closing of RL1 provides constant coil energizing after the shutdown event. Therefore, when the vibration level drops below the alarm threshold level after shutdown, the closed RL1 contacts still energize the RL coil and keep RL2 in the open position. The Reset pushbutton should be pushed to reset the 2-wire switch, close the RL2 contacts and open the RL1 contacts before restarting the motor.

Both Alarm Siren and Automatic Machinery Shutdown Using Two Switches

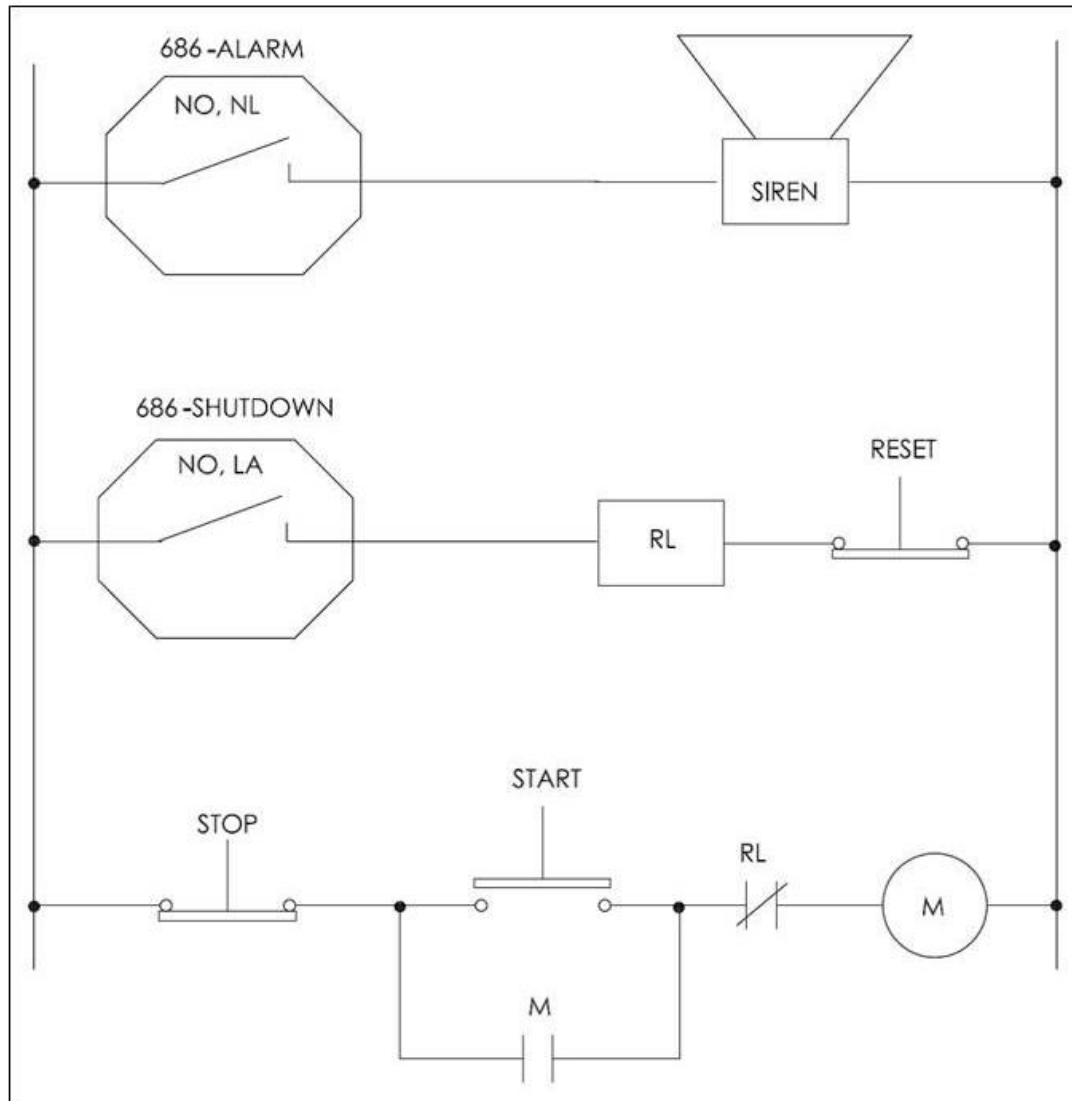


Figure 22 – Both Alarm Siren and Automatic Machinery Shutdown Using Two Switches

The Smart Switches are hooked up for providing alarm siren and automatic motor shutdown when the alarm threshold levels are exceeded. To accomplish this, the two switches have two different threshold values; one for alarm and one for shutdown. Pushing the Start pushbutton closes the M contact, and since RL2 contacts are normally closed, starts the motor. If the start-up delay option for the switch is enabled, the switch will not trip regardless of the vibration level during the specified delay time. After this delay, if the vibration level exceeds the alarm threshold for the alarm switch, it will be activated and apply a voltage to the alarm siren. Since the NL (non-latching) option is specified for this switch, the alarm siren will be energized until the vibration level falls below the alarm threshold value (based also on the specified hysteresis). If the vibration level exceeds the shutdown alarm threshold, the second vibration switch will be activated and apply a voltage to the RL relay coil. This will open the RL contacts and shut down the motor. Since the LA (latching) option is specified, the RL coil will be constantly energized after this event; even though the vibration level will drop below the alarm threshold value after shutdown. The Reset pushbutton should be pushed to reset the switch and close the RL contacts before restarting the motor.

Automatic Machinery Shutdown Based on Normally Open Solid-State Relay

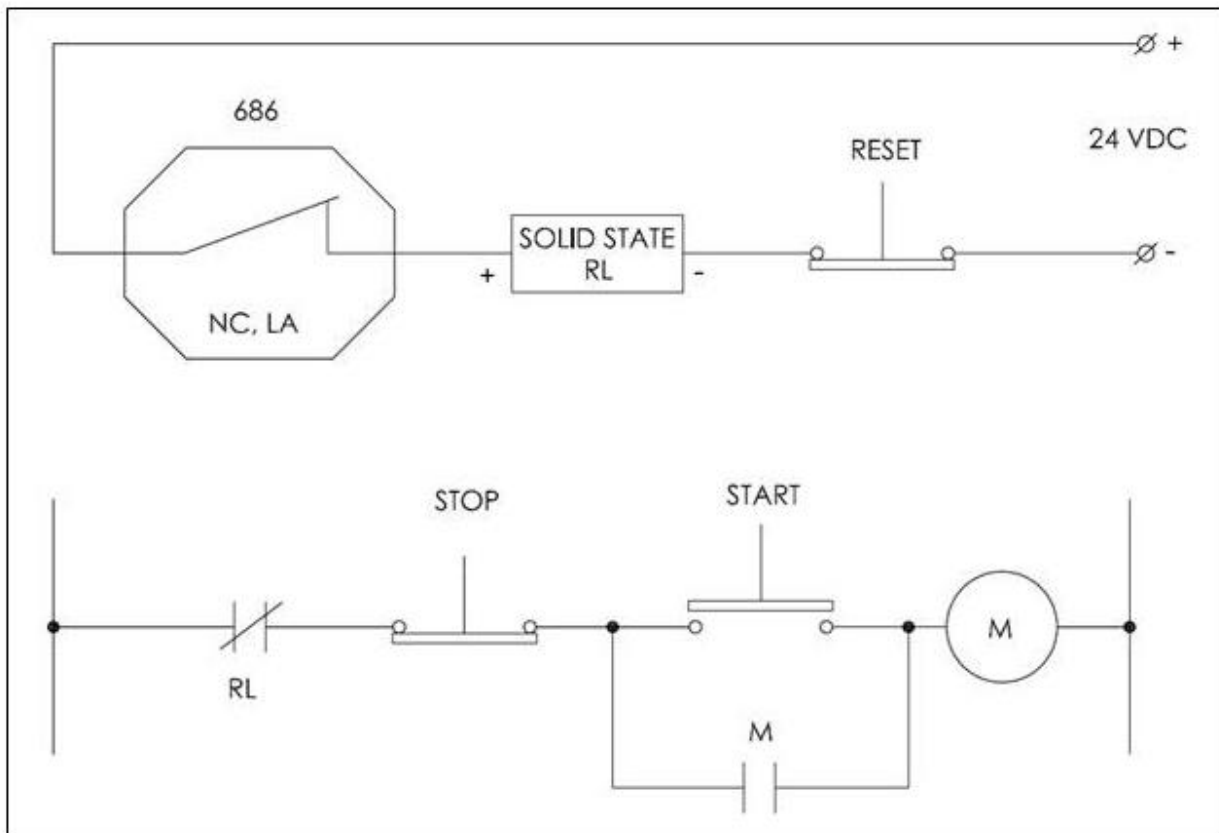


Figure 23 – Automatic Machinery Shutdown Based on Normally Open Solid-State Relay

The Smart Switch is hooked up to provide automatic motor shutdown when the alarm threshold level is exceeded. Pushing the Start pushbutton closes the M contact, and since the switch is Normally Closed, the solid state relay will be energized and the RL contacts will be closed. This will start the motor. If the start-up delay option is enabled, the switch will not trip regardless of the vibration level during the specified delay time. After this delay, if the vibration level exceeds the alarm threshold, it will be activated, thereby opening its contacts and de-energizing the solid state relay input. This will open the RL contacts and shut down the motor. Since the LA (latching) option is specified, the solid state relay input will be constantly de-energized after this event even if the vibration level drops below the alarm threshold value after shutdown. The Reset pushbutton should be pushed to reset the switch and close the RL contacts before restarting the motor.

Automatic Machinery Shutdown of Three-Phase Electrical Motor Based on a N.O. Solid State Relay

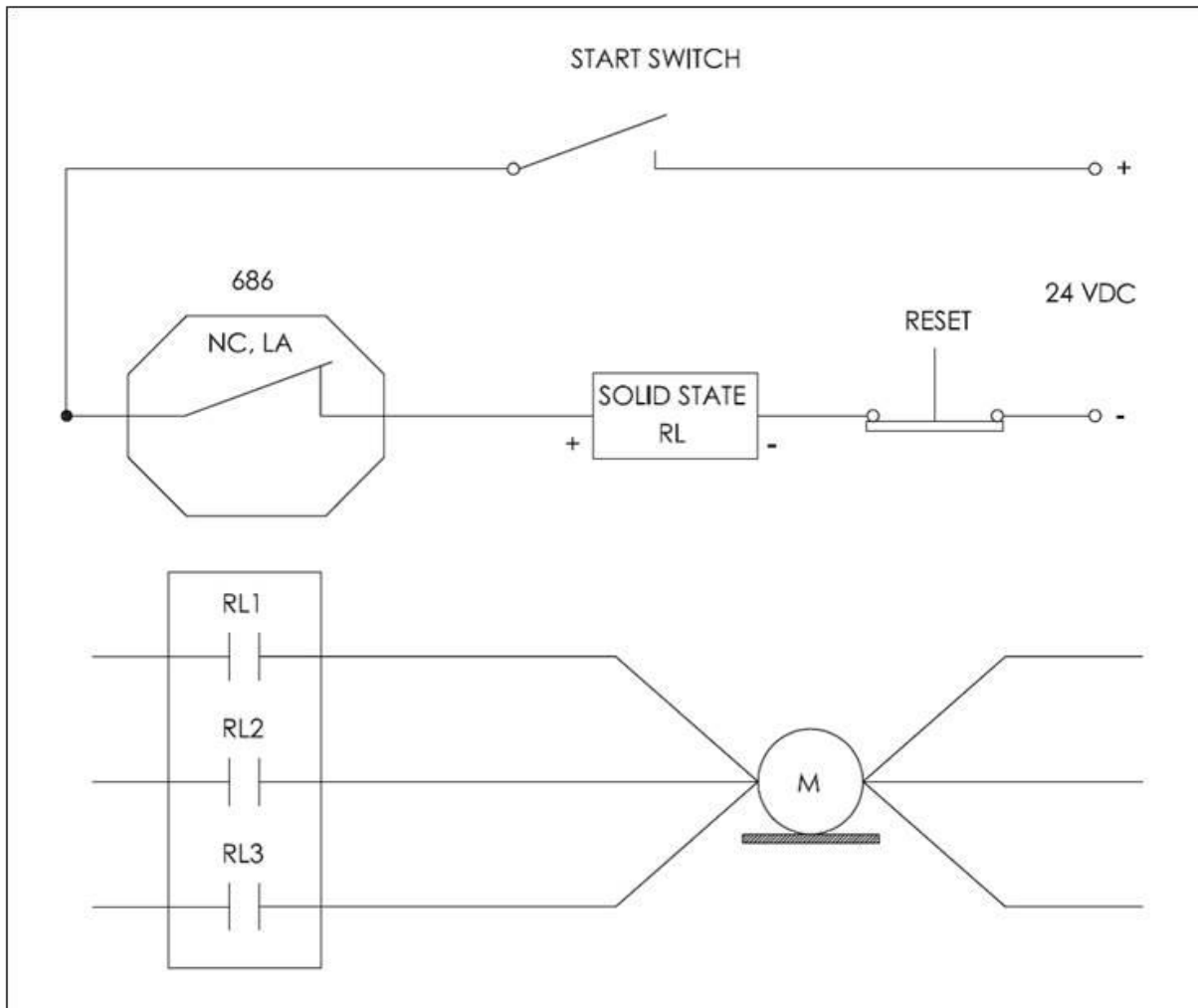


Figure 24 – Automatic Machinery Shutdown of 3-Phase Electrical Motor Based on a N.O. Solid State Relay

The Smart Switch is hooked up to provide automatic motor shutdown when the alarm threshold level is exceeded using a normally open three channel solid state relay. Since the Smart Switch is normally closed, closing the Start Switch will energize the solid state relay. This will cause the RL1, RL2, and RL3 contacts to close and start the motor. If the start-up delay option for the switch is enabled, the switch will not trip regardless of the vibration level during the specified delay time. After this delay, if the vibration level exceeds the alarm threshold, it will be activated, thereby opening its contacts and de-energizing the solid state relay input. This will open the RL1, RL2, & RL3 contacts and shut down the motor. Since the LA (latching) option is specified, the solid state relay input will be constantly de-energized after this event; even if the vibration level drops below the alarm threshold value after shutdown. The Reset pushbutton should be pushed to reset the switch and close the RL1, RL2, & RL3 contacts before restarting the motor. This will start the motor immediately without using the Start pushbutton.

Programming Software

The Smart Switch can be user-programmed with the optional Model 600A29 Programming Kit. The kit includes USB programmer cable/dongle (Model 070A100), software (Model EE225), terminal block/integral cable adapter (Model 042M17) and magnet clip (Model 080A214). The software can also be downloaded from IMI's website, www.pcb.com. This software must be installed prior to connecting the Smart Switch to the computer using the USB programmer cable. The software includes both the drivers and user interface needed for programming the Smart Switch. During initial installation, you may need administrative rights for the computer in order to install the drivers. Once installed, administrative rights are not required for use.



Figure 25 – Model 600A29 USB Programmer Kit

Program Installation

Installing the Software and USB Driver: Insert the software CD provided into the CD drive. The software will start the installation automatically if your PC is set to auto-install applications. If not, browse the CD and click on Setup.exe to start the installation process. The default installation directory is C:\PCB\EE225. It is recommended to use the default setting.

The installer will first install the software and then the WinUSB device driver. This device driver is required for the programmer software to communicate with the 070A100 USB programmer cable included in the programmer kit.

The following screens will be displayed when the installer starts. Click the Next button to proceed from step to step.

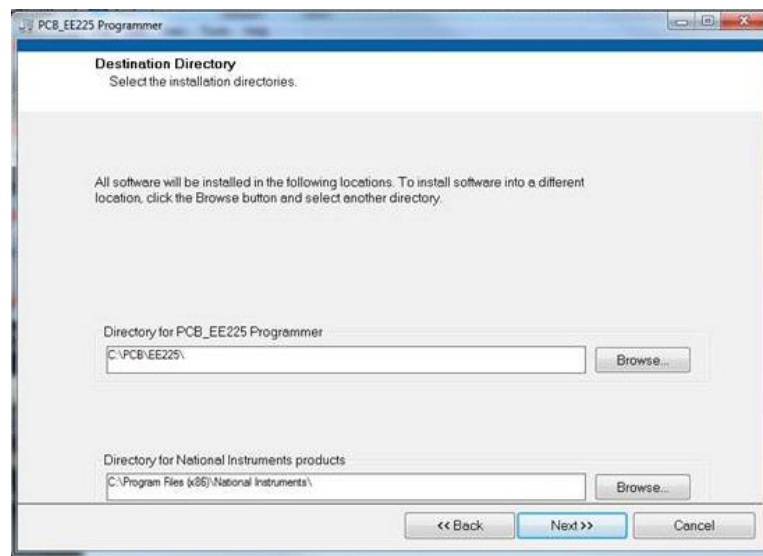


Figure 26 – Install Location Screen

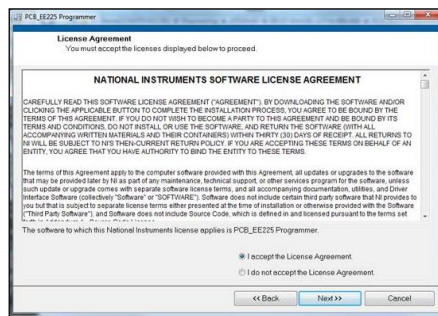


Figure 27 – National Instruments Software License Agreement

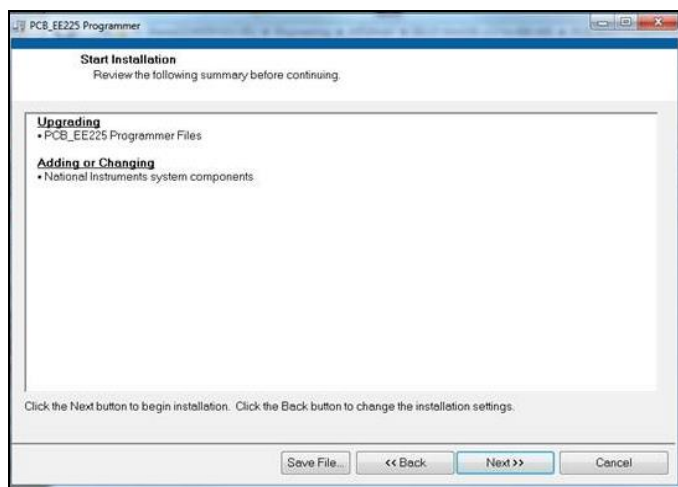


Figure 28 – Installation Verification Screen

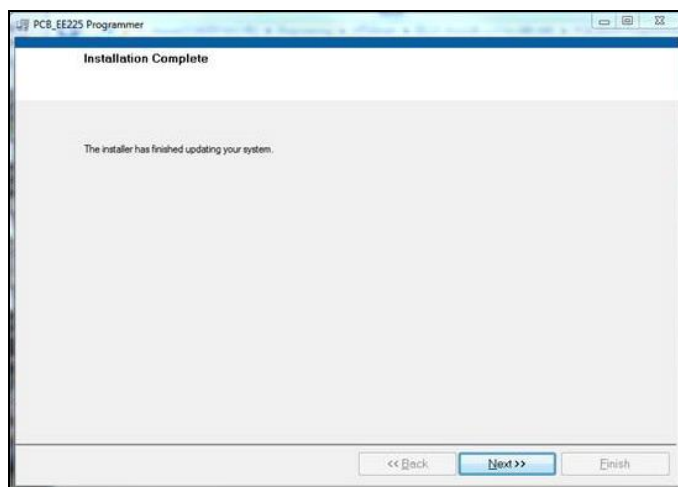


Figure 29 – Installation Complete Screen

After the software completes, the USB driver installer will start automatically. The initial USB installer will look similar to the one below.



Figure 30 – WinUSB Driver Installation Screen

The drivers will now be properly installed and you should get the following screen. Click “Finish”. The software is now ready to use.



Figure 31 – WinUSB Driver Installation Complete Screen

Running the Software

Connect the USB programmer cable to the Smart Switch. Hold a magnet to the indicated MAVT™ point on the Smart Switch. Wait about 2 seconds. While keeping the magnet against the Smart Switch, connect the USB programmer cable to a USB port on the PC. Run the software from the Start | All Programs | PCB EE225 Software menu item.

Initially the screen will appear as in **Error! Reference source not found.** with a yellow bar and status indicating 'Initializing...' followed by the message: "Connecting to USB Dongle..."

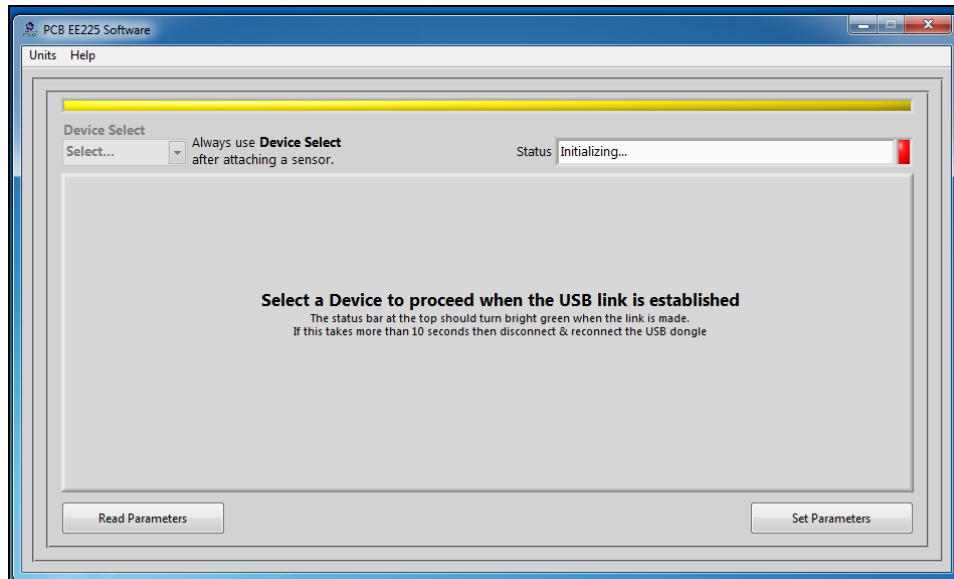


Figure 32 – Software While Connecting to USB Programmer Cable

Once the connection is made the bar at the top of the screen will turn green and the status will indicate "USB Connection Success - Select a device". If the software and USB programmer cable fail to connect, remove and reinsert the USB programmer cable.

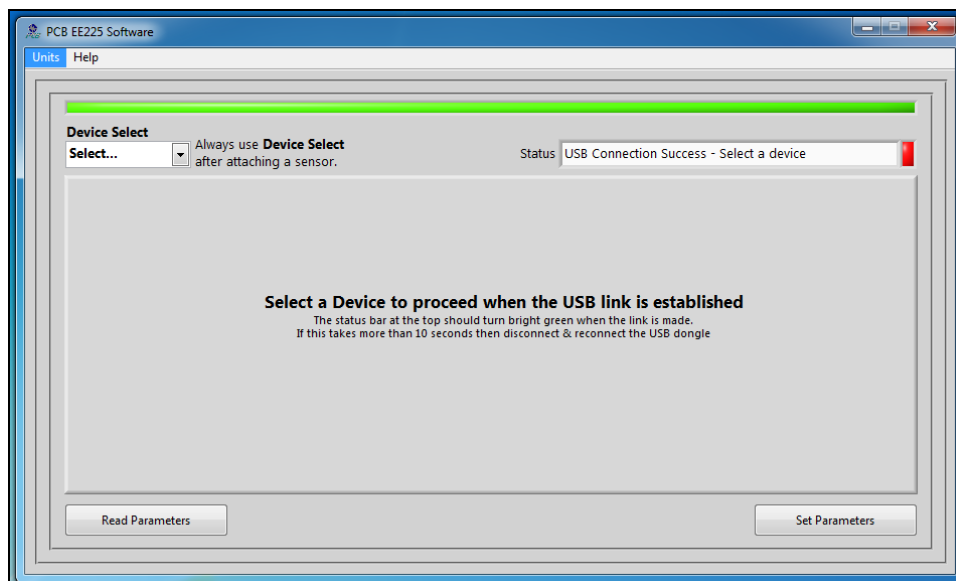


Figure 33 – Software After Connecting to USB Programmer Cable

To select a device, click on the Device Select pull down menu and select the device you'd like to program. In this case, select 686.

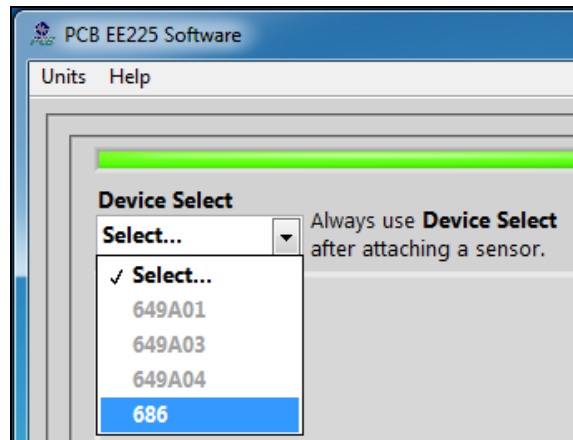


Figure 34 – Device Selection

Once a product is selected, the software will prompt you to confirm connection of the sensor to the PC using the USB programmer cable. Click OK to proceed.

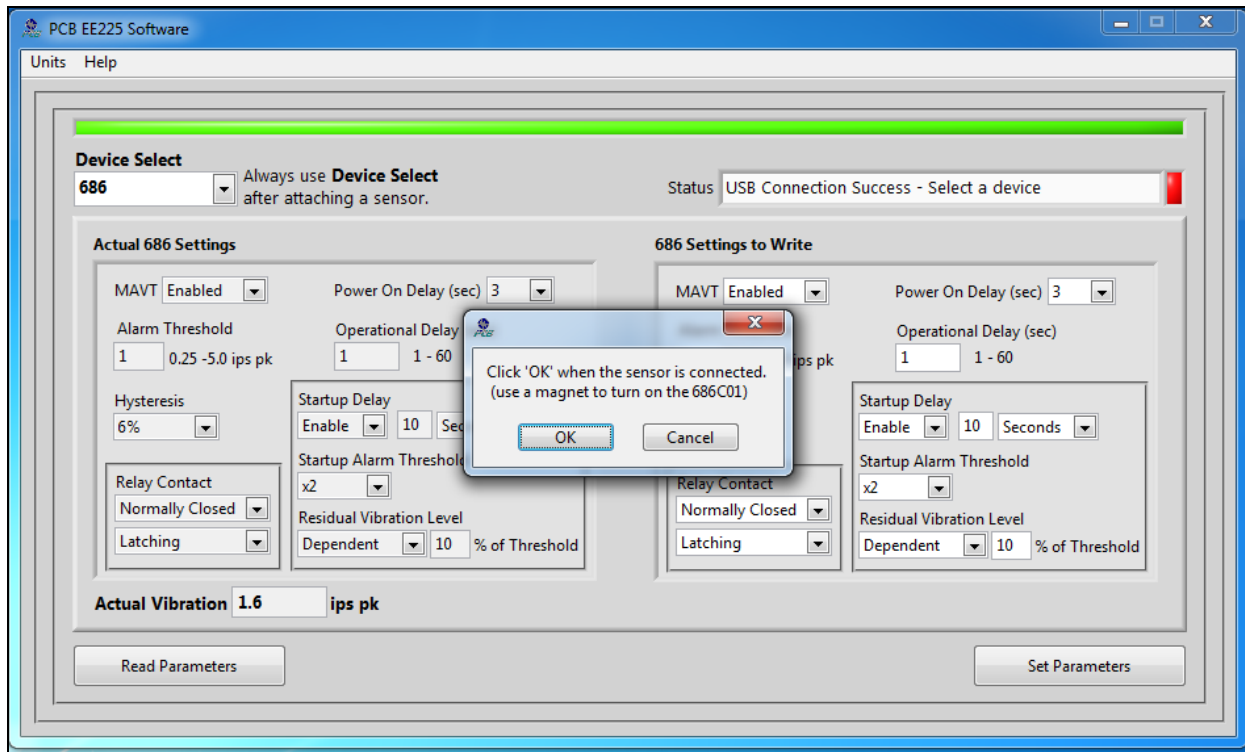


Figure 35 – Sensor Connection Screen

While the software is establishing communication with the sensor, the status will display 'Checking Status...' and the colored indicator box next to the status will alternate between red and yellow. This will take approximately 15 seconds. Once communication is established, the indicator box will turn green and the software will read the sensor's current settings and data. The fields presented in the main body of the screen will be specific to the selected sensor.

Programming Sections

The screen has two sections:

- Actual 686 Settings – This section shows the settings currently programmed in the sensor.
- 686 Settings to Write – This section shows the options for programming the sensor.

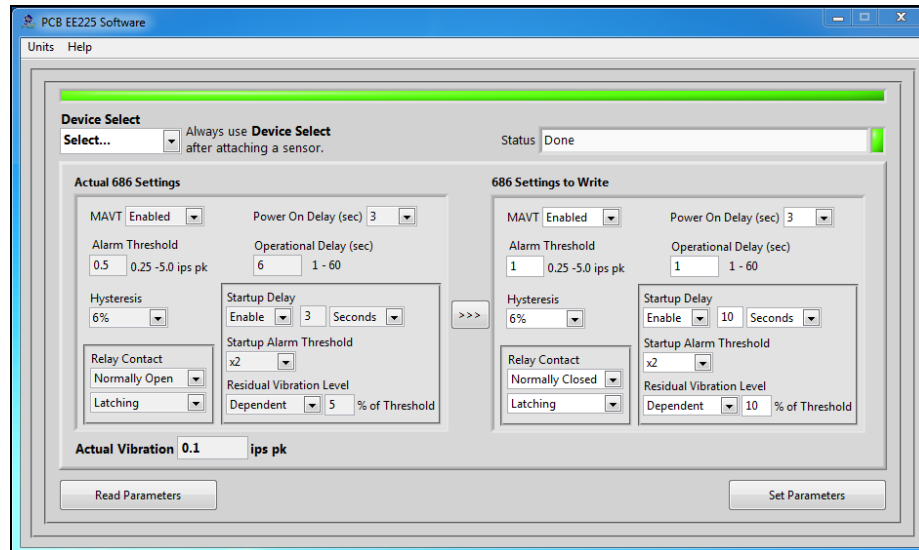


Figure 36 – Typical Smart Switch Screen After Successful Parameter Read

Reading and Writing Parameters

- Reading Parameters - To read the current sensor settings, click the Read Parameters button. This operation takes approximately 45 seconds to complete.
- Transferring Actual Settings to Settings to Write Field - Use the '>>>' button to transfer all Actual Settings to the Settings to Write fields.
- Writing Parameters- Select the appropriate mode and enter any pertinent parameter information. Click the Set Parameters button. This causes the settings to be sent to the sensor and then read back and displayed in the Actual 686 Settings.

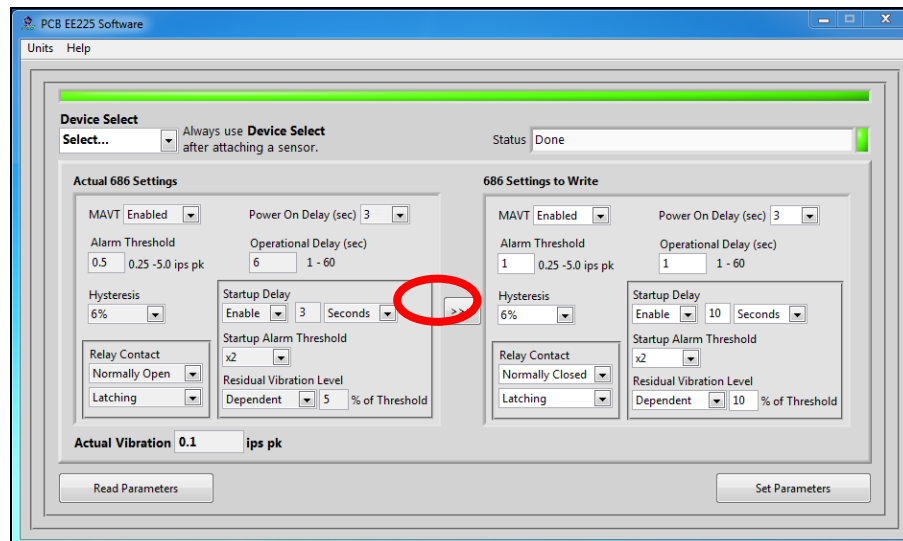


Figure 37 – Transferring Actual Settings to Settings to Write Field

Parameter Options

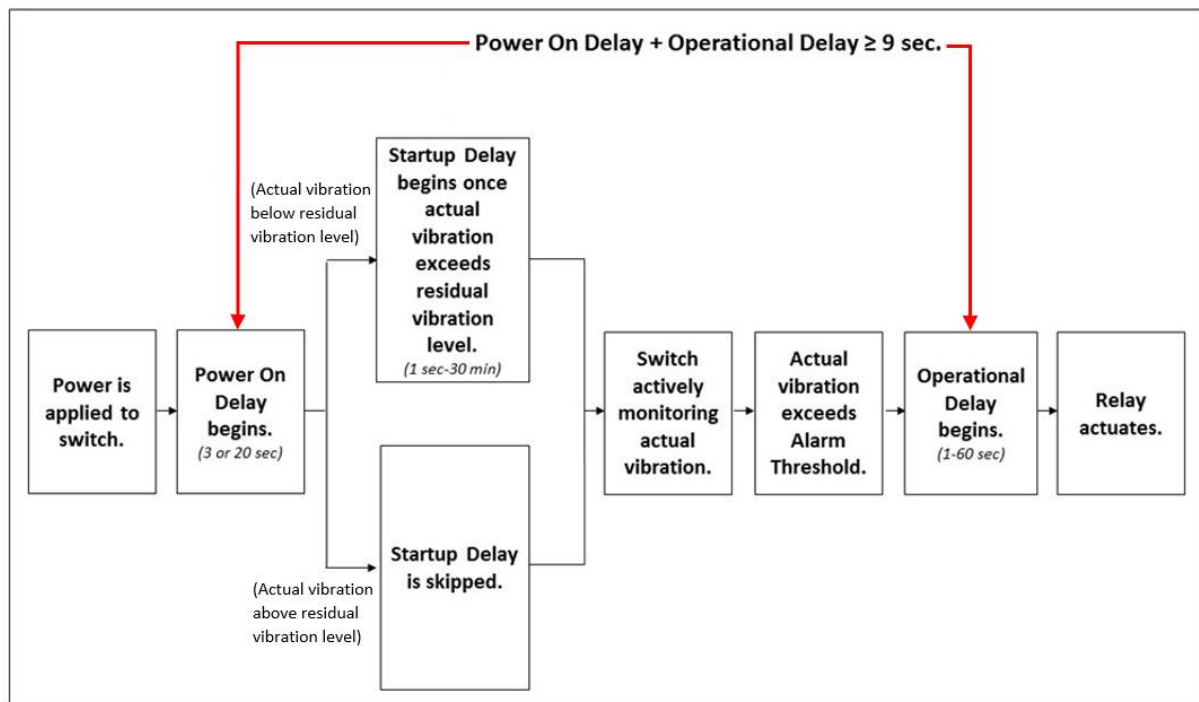
The software presents one read-only parameter (Actual Vibration) and several parameters that can be programmed to optimize performance of the Smart Switch. At any point during the programming process, the values can be changed between imperial and metric measurements by clicking the Units dropdown in the top navigation menu and then selecting the appropriate measurement type.

Parameter	Description	Acceptable Value(s)
Actual Vibration	Actual vibration (ips pk) being sensed by the switch at time when Read Parameters button is clicked.	N/A
MAVT™	Capability to determine and set the alarm threshold value automatically by the Smart Switch based on the actual vibration level measured by it. For more information about the MAVT™ feature, see page 16.	Enabled Disabled
Alarm Threshold	Vibration level at which the relay will change state.	0.25- 5.0 ips pk 6.35-127 mm/s pk
Hysteresis	Percentage that actual vibration must fall below the alarm threshold in order for a non-latching relay to automatically reset itself. Hysteresis prevents a relay from continually changing states when the vibration level is hovering around the alarm threshold level.	3% 6% 10%
Relay Contacts- Normal State	State in which the relay stays when not tripped.	Normally Open Normally Closed
Relay Contacts- Reset State	How the relay operates once actual vibration falls below the alarm threshold. - Latching: Relay to latch or stay in the alarm state until manually reset regardless of the vibration level. - Non-Latching Relay automatically resets once the vibration level falls below the alarm threshold (hysteresis) level.	Latching Non-Latching
Power On Delay	Specified time period immediately after power is applied to the switch during which the relay will not trip regardless of the vibration level. Prevents a relay trip during high transient vibration levels that may occur during a normal machine startup.	3 sec 20 sec
Operation Delay	Specified time period for which actual vibration must constantly exceed the Alarm Threshold before the relay changes state. Prevents a relay trip as a result of a short transient spike in vibration level that may not even be caused by a machine fault.	1-60 sec
Startup Delay- Status	Specified time period immediately after power is applied to the equipment being monitored during which the relay will not trip regardless of vibration level.	Enabled Disabled
Startup Delay- Time Period	Time period during which vibration is ignored.	1-60 sec 1-30 min
Startup Delay- Startup Alarm Threshold	Maximum vibration ignored during the time period. Calculated as a multiple of the Alarm Threshold.	2x 4x 8x Blocked (All vibration)
Startup Delay- Residual Vibration Level	Minimum vibration level that, once surpassed at equipment startup, triggers the countdown of the Startup Delay Time Period.	Dependent (Threshold %) Independent (Value) Max 40% of Threshold

Unless otherwise specified, the Smart Switch comes from the factory with a set of default parameters. The specific set of parameters depends on the last alphanumeric character in the model number.

		Last Alphanumeric Character				
		1	2	3	4	X
Parameter	MAVT™	Enabled				Custom, Customer-Specific Configuration
	Alarm Threshold	0.60 ips				
	Hysteresis	6%				
	Relay Contacts-Normal State	Normally Open	Normally Closed	Normally Open	Normally Closed	
	Relay Contacts-Reset State	Latching	Latching	Non-Latching	Non-Latching	
	Power On Delay	3 sec				
	Operation Delay	6 sec				
	Startup Delay-Status	Enabled				
	Startup Delay-Time Period	3 sec				
	Startup Delay-Startup Alarm Threshold	2x				
	Startup Delay-Residual Vibration Level	Dependent 5% of Threshold				

Execution of Delays



Magnetically Adjustable Vibration Threshold (MAVT™)

Magnetically Adjustable Vibration Threshold (MAVT™) is a Smart Switch selectable feature via USB programming. This unique capability allows the alarm threshold value to be determined and set automatically by the Smart Switch based on the actual vibration level being measured by it. This convenient feature permits any machine to be protected by a vibration switch within seconds without knowing anything about its vibration levels.

The Smart Switch has no accessible mechanical adjustments (ie. screw pots or DIP switches) that are found on other style electronic vibration switches. However, when the MAVT™ option is selected, the hermetically-sealed switch becomes adjustable through magnetic actuation. By touching a specified location on the housing with a strong permanent magnet for 2 seconds, an internal microprocessor is actuated that initiates the test sequence.

Note: The magnet clip (Model 080A214) is a supplied accessory when the Smart Switch is ordered from the factory with the optional 600A29 USB Switch Programmer Kit.



Figure 38 – Magnet Clip

MAVT™ Procedure

Be absolutely sure you do not have the switch connected to the machine's trip circuit during this procedure as the trip relay is activated several times during the procedure and will cause the machine to shut down and turn on several times. This could cause damage to your machinery.

1. Mount the Smart Switch on the machine that the switch will monitor. Be sure that the machine is operating in a steady state condition. If it is not operating, turn the machine on and allow enough time for the vibration level to normalize before going to the next step.
2. Connect the switch to the power supply using an appropriate cable. Since the Smart Switch operates off universal power, any power supply that outputs 24-240 VDC or 24-240 VAC, 50/60 Hz will work. A simple 24V power supply/signal conditioner (Model 480C02) will also work well and has the added advantage of visually indicating when the calibration process has been completed via its built-in meter. Allow 30 seconds for the switch to power up.
3. Touch the permanent magnet to the target on the side of the switch for approximately 2 seconds to initiate the process.
4. The alarm threshold calibration process takes approximately 30 seconds. (The amount of time needed varies based on the difference between the previous and new alarm threshold values.) During this process, the unit will measure the average vibration amplitude, set the alarm threshold value to two times this average value and store this value in a non-volatile memory. The relay contacts open and close repeatedly during this process.
5. Disconnect the Smart Switch from the power supply.
6. The switch can now be permanently installed on the machine for protection.

Switch Model Number Template

Prefix Option

- Blank** No Prefix Option
EX CSA Approval
M Metric Stud (Not w/ Terminal Block)
EXM Metric Stud, CSA Approval (Not w/ Terminal Block)

Version

- B** B Version (All models except those listed for C version)
C C Version (Models 686C01 & 686C0X only)

Electrical Connection

- 0** 2-Pin Mil-C-5015 Connector
1 Integral Cable
6 Integral Armored Cable
7 Terminal Block

Program Configuration

- 1** 1 0 060 1 06 0 0 1 0 03 0 0 005
2 " " " " " 1 " " " " " " "
3 " " " " " 2 " " " " " " "
4 " " " " " 3 " " " " " " "
X Custom Program Configuration (Fill out form below)

Use for Integral Cable Models Only

Cable Length Units

- Blank** English (ft)
M Metric (m)

Cable Length

- 001 to 200** Cable Length in ft
001 to 060 Cable Length in m

Cable Termination

- AB** BNC Jack
AC BNC Plug
AD Pigtail
BZ Blunt Cut

Armor Length

- Blank** Same as Cable Length
001 to 050 Armor Length in ft
001 to 015 Armor Length in m

Suffix Option

- Blank** No Suffix Option
D ATEX/IECEx Ex d Approval
 (EX prefix must also be selected)

Custom Program Configuration

MAVT™

A

0	Disabled
1	Enabled

Alarm Threshold

B

0	English
1	Metric

C Value = 0.25 to 5.00 ips pk
 04.5 to 90.0 mm/sec pk

e.g.: 0.25 ips =

0	2	5
2	5	4

25.4 mm/sec =

Hysteresis

D

0	3%
1	6%
2	10%

Operational Delay

E

Value = 01 to 60 sec

Relay Contact

F

0	Latching, Normally Open
1	Latching, Normally Closed
2	Non-Latching, Normally Open
3	Non-Latching, Normally Closed

Power On Delay

G

0	3 sec
1	20 sec

Startup Delay

H

0	Disabled
1	Enabled

I

0	Seconds
1	Minutes

J Value = 01 to 60 sec, or
 01 to 30 min.

Alarm Threshold During Startup

(Multiplier of the Alarm Threshold)

K

0	x2
1	x4
2	x8
3	Blocked

Residual Vibration Level

L

0	Dependent
1	Independent

M

Value = For **Dependent** 001 to
 040% of Alarm Threshold.
 For **Independent**
 0.01 to 5.00 ips
 00.1 to 90.0 mm/sec

Figure 39 – Ordering Guide

Battery-Powered Signal Conditioner

Power supply/signal conditioner (Model 480C02) is for use with the Smart Switch when determining the alarm threshold level using the MAVT™ feature. The built-in meter indicates when the process is complete. See www.pcb.com for product details.



Figure 40 – Battery Powered Signal Conditioner

Calibration Cable

The calibration cable (Model 052BR010AC) is a 10 foot, twisted-pair, shielded cable with a 2-Pin MIL type connector terminating to a BNC plug for use with 480C02 power supply and Smart Switch.



Figure 41 – Calibration Cable

Magnet Clip

The magnet clip (Model 080A214) is supplied as part of the optional 600A29 USB Programmer Kit or can be ordered separately for use with the MAVT™.



Figures 42 and 43 – Magnet Clip with and without Smart Switch

Cable Ordering Information

Go to www.pcb.com for complete information on cables.

IMI Part Number: **052** **BR** **010** **BZ**

Cable Model Series

052 Polyurethane, Shielded, Twisted Pair
048 Armored Polyurethane, Shielded, Twisted Pair

Switch Connector Type

AE 2 socket MIL type with environmental boot
BP 2 socket MIL type high temp with strain relief
BR 2 socket MIL type molded composite
BQ 2 socket MIL type molded composite, right angle

Cable Length

010 10 feet
020 20 feet
030 30 feet
040 40 feet
050 50 feet
XXX Any length

Cable termination

BZ Blunt Cut

(Consult factory for additional options)



Warning 1 – ESD sensitivity

The power supply/signal conditioner should not be opened by anyone other than qualified service personnel. This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the safety precautions required to avoid injury.

Warning 2 – ESD sensitivity

This equipment is designed with user safety in mind; however, the protection provided by the equipment may be impaired if the equipment is used in a manner not specified by PCB Piezotronics, Inc.

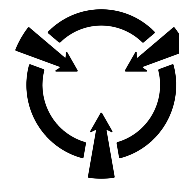
Caution 1 – ESD sensitivity

Cables can kill your equipment. High voltage electrostatic discharge (ESD) can damage electrical devices. Similar to a capacitor, a cable can hold a charge caused by triboelectric transfer, such as that which occurs in the following:

- *Laying on and moving across a rug,*
- *Any movement through air,*
- *The action of rolling out a cable, and/or*
- *Contact with a non-grounded person.*

The PCB solution for product safety:

- *Connect the cables only with the AC power off.*
- *Temporarily “short” the end of the cable before attaching it to any signal input or output.*



CAUTION
ELECTROSTATIC
DISCHARGE SENSITIVE

Caution 2 – ESD sensitivity

ESD considerations should be made prior to performing any internal adjustments on the equipment. Any piece of electronic equipment is vulnerable to ESD when opened for adjustments. Internal adjustments should therefore be done ONLY at an ESD-safe work area. Many products have ESD protection, but the level of protection may be exceeded by extremely high voltage.

Warranty

IMI instrumentation is warranted against defective material and workmanship for 1 year unless otherwise expressly specified. Damage to instruments caused by incorrect power or misapplication, is not covered by warranty. *If there are any questions regarding power, intended application, or general usage, please consult with your local sales contact or distributor.* Batteries and other expendable hardware items are not covered by warranty.

Service

Because of the sophisticated nature of IMI instrumentation, field repair is typically **NOT** recommended and may void any warranty. If factory service is required, return the instrumentation according to the "Return Procedure" stated below. *A repair and/or replacement quotation will be provided prior to servicing at no charge.* Before returning the unit, please consult a factory IMI applications engineer concerning the situation as certain problems can often be corrected with simple on-site procedures.

Return Procedure

To expedite returned instrumentation, contact a factory IMI applications engineer for a RETURN MATERIAL AUTHORIZATION (RMA) NUMBER. Please have information available such as model and serial number. Also, to insure efficient service, *provide a written description of the symptoms and problems with the equipment to a local sales representative or distributor, or contact IMI if none are located in your area.*

Customers outside the U.S. should consult their local IMI distributor for information on returning equipment. For exceptions, please contact the International Sales department at IMI to request shipping instructions and an RMA. For assistance, please call (716) 684-0003, or fax us at (716) 684-3823. You may also receive assistance via e-mail at imi@pcb.com or visit our web site at www.pcb.com.

Customer Service

IMI, a division of PCB Piezotronics, guarantees **Total Customer Satisfaction**. If, at any time, for any reason, you are not completely satisfied with any IMI product, IMI will repair, replace, or exchange it at no charge. You may also choose to have your purchase price refunded.

IMI offers to all customers, at no charge, 24-hour phone support. This service makes product or application support available to our customers, day or night, seven days a week. When unforeseen problems or emergency situations arise, call the **IMI Hot Line at (716) 684-0003**, and an application specialist will assist you.

Model Number 686B72		SMART VIBRATION SWITCH		Revision: A ECN #: 39883											
Performance		ENGLISH	SI	OPTIONAL VERSIONS											
Alarm Threshold(± 10 %)		0.25 to 5 in/sec pk	4.5 to 90 mm/s rms	Optional versions have identical specifications and accessories as listed for the standard model except where noted below. More than one option may be used.											
Frequency Range(± 3 dB)		420 to 60 kcpm	7 to 1000 Hz												
Hysteresis(% < Alarm Threshold)		3; 6; or 10 %	3; 6; or 10 %	EP - Explosion-proof certified conduit housing with 1" pipe thread											
Residual Vibration Level(Reference)		Dependent or Independent	Dependent or Independent	EX - Hazardous Area Approval- contact factory for specific approvals											
Residual Vibration Level(% Alarm Threshold)		1 to 40 %	1 to 40 %	Hazardous Area Approval CI I, Div 2, Groups A, B, C, D; ExnA IIC T3, AExnA IIC T3											
MAVT(Sets Alarm Threshold to 2X actual vibration)		Enabled or Disabled	Enabled or Disabled												
Transverse Sensitivity		<3 %	<3 %												
Power On Delay(± 1 sec)		3 or 20 sec	3 or 20 sec												
Startup Delay(± 1 sec or 1 min)(Time)		1 to 60 sec or 1 to 30 min	1 to 60 sec or 1 to 30 min												
Startup Delay(x Alarm Threshold)		x2; x4; x8; Blocked	x2; x4; x8; Blocked												
Startup Delay(Active)		Enabled or Disabled	Enabled or Disabled												
Operational Delay(± 1 sec)		1 to 60 sec	1 to 60 sec												
Relay(Type)		SPST, Form A or B	SPST, Form A or B												
		MOSFET	MOSFET												
Relay(Capacity)		24 to 240 V AC/DC, 500 mA	24 to 240 V AC/DC, 500 mA												
Relay(Latching)		Latching / Non-Latching	Latching / Non-Latching												
Relay(Contacts)		Normally Open / Closed	Normally Open / Closed												
Environmental				NOTES:											
Temperature Range(Operating)		-40 to 185 °F	-40 to 85 °C	[1] USB Programmable - See configuration sheet supplied with switch for exact setting.											
Temperature Range(Storage)		-40 to 257 °F	-40 to 125 °C	[2] See PCB Declaration of Conformance PS023 or PS060 for details.											
Overload Limit(Shock)		5000 g pk	49,050 m/s ² pk												
Electrical															
Power Required		24 to 240 V DC/AC 50/60 Hz	24 to 240 V DC/AC 50/60 Hz												
Current Rating(Relay Closed)		500 mA	500 mA												
Leak Current(Relay Open)		≤ 1 mA	≤ 1 mA												
Electrical Isolation(Case)		>10 ⁸ Ohm	>10 ⁸ Ohm												
Physical															
Size (Hex x Height)		1.38 in x 3.68 in	1.38 in x 94 mm												
Weight		7.0 oz	200 gm												
Mounting Thread		1/4 NPT	No Metric Equivalent												
Sensing Element(Internal)		Piezoelectric Accelerometer	Piezoelectric Accelerometer												
Housing Material		Stainless Steel	Stainless Steel												
Electrical Connector		Terminal Block	Terminal Block												
Electrical Connection Position		Top	Top												
Screw Terminal Wire Size		12-24 AWG	3.0 - .2mm ²												
Conduit Housing Thread		1" NPT Female	No Metric Equivalent												
 [2] 		<table><tr><td>Entered: AP</td><td>Engineer: do</td><td>Sales: EGY</td><td>Approved: BAM</td><td>Spec Number:</td></tr><tr><td>Date: 9/4/2012</td><td>Date: 9/4/2012</td><td>Date: 9/4/2012</td><td>Date: 9/4/2012</td><td>43747</td></tr></table>				Entered: AP	Engineer: do	Sales: EGY	Approved: BAM	Spec Number:	Date: 9/4/2012	Date: 9/4/2012	Date: 9/4/2012	Date: 9/4/2012	43747
Entered: AP	Engineer: do	Sales: EGY	Approved: BAM	Spec Number:											
Date: 9/4/2012	Date: 9/4/2012	Date: 9/4/2012	Date: 9/4/2012	43747											
 A PCB PIEZOTRONICS DIV. 3425 Walden Avenue, Depew, NY 14043		Phone: 800-959-4464 Fax: 716-684-3823 E-Mail: imi@pcb.com													

All specifications are at room temperature unless otherwise specified.
In the interest of constant product improvement, we reserve the right to change specifications without notice.

2

1

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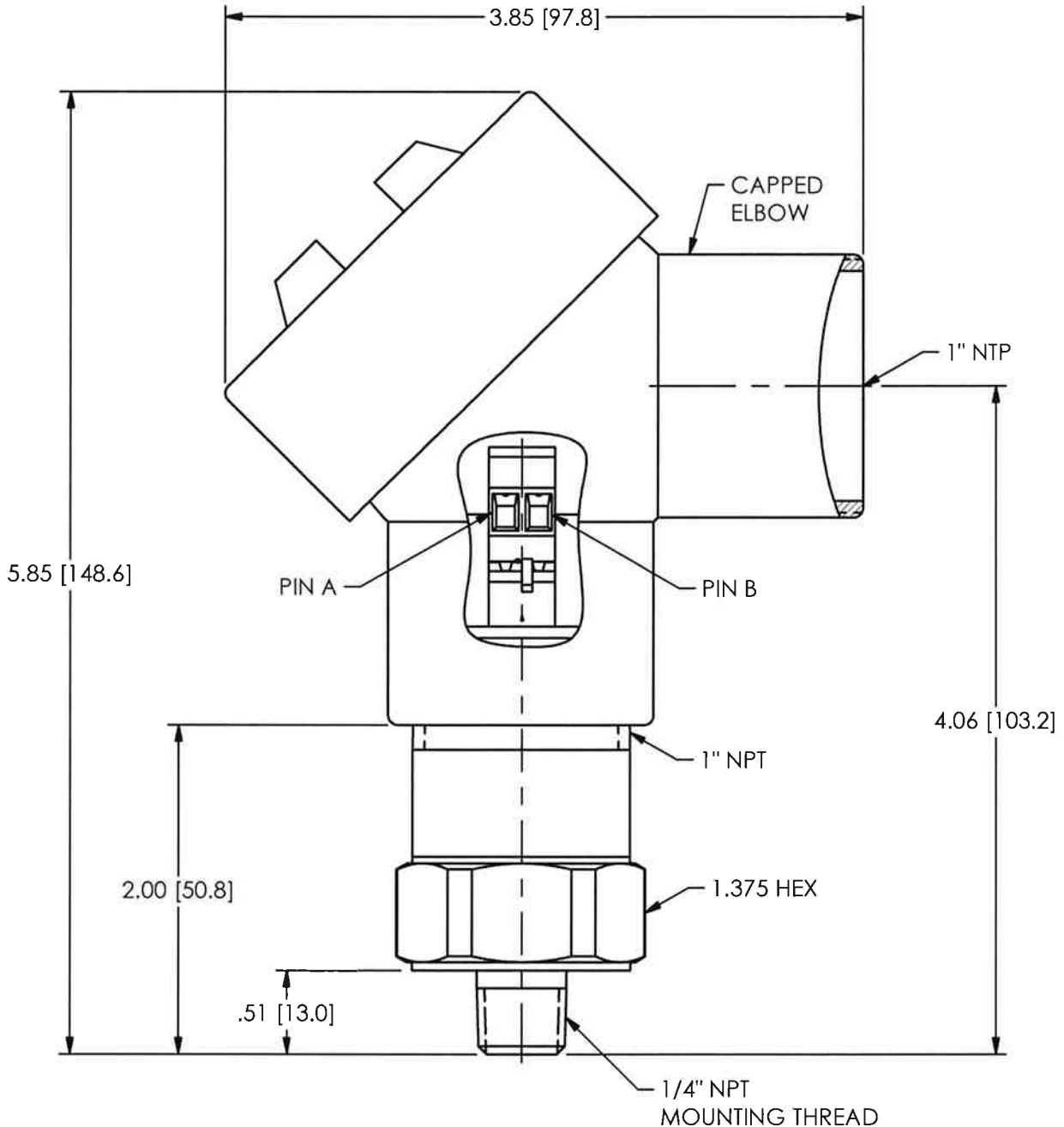
REVISIONS

REV	DESCRIPTION	ECO
A	ADDED RELATED STAMP	30762
B	UPDATE TITLE BLOCK	31223

42338

RELATED DRAWING

NO MODIFICATIONS PERMITTED
WITHOUT THE APPROVAL OF
THE AUTHORIZED PERSON



UNLESS OTHERWISE SPECIFIED TOLERANCES ARE:

DIMENSIONS IN INCHES

DECIMALS XX ± 0.03
XXX ± 0.10

ANGLES ± 2 DEGREES

FILLETS AND RADII
.003 - .005

DIMENSIONS IN MILLIMETERS
[IN BRACKETS]

DECIMALS X ± 0.8
XX ± 0.25

ANGLES ± 2 DEGREES

FILLETS AND RADII
0.07 - 0.13

DRAWN

MDF

8/27/09

CHECKED

ECS

8/28/09

ENGINEER

JJD

8/27/09

TITLE

OUTLINE DRAWING
MODEL EP686B7X & EX686B7X
VIBRATION SWITCH



PCB PIEZOTRONICS^{INC}

3425 WALDEN AVE. DEPEW, NY 14043
(716) 684-0001 E-MAIL: sales@pcb.com

CODE
IDENT. NO.
52681

DWG. NO.

42338

SCALE: FULL

SHEET 1 OF 1

2

1



LCIE

1 ATTESTATION D'EXAMEN DE TYPE VOLONTAIRE

- 2 **Appareil** destiné à être utilisé en atmosphères explosibles (Directive 94/9/CE)
 - 3 Numéro de l'attestation d'examen de type
LCIE 10 ATEX 1008 X
 - 4 Appareil
Capteur de vibrations
Type : EX686B series
 - 5 Demandeur : PCB Piezotronics
Adresse : 3425 Walden Avenue
Depew, New York 14043 USA
 - 7 Cet appareil et ses variantes éventuelles acceptées sont décrits dans l'annexe de la présente attestation et dans les documents descriptifs cités en référence.
 - 8 Le LCIE certifie que cet appareil est conforme aux exigences essentielles de sécurité et de santé pour la conception d'appareils, électriques de catégorie 3 ou non électriques de catégorie 2 et 3, destinés à être utilisés en atmosphères explosibles, données dans l'annexe II de la directive 94/9/CE du Parlement européen et du Conseil du 23 mars 1994.
- Les résultats des vérifications et essais figurent dans le rapport confidentiel N° 93796/586962.
- 9 Le respect des exigences essentielles de sécurité et de santé est assuré par la conformité à :
- EN 60079-0 (2006)
- EN 60079-15 (2005)
 - 10 Le signe X lorsqu'il est placé à la suite du numéro de l'attestation, indique que cet appareil est soumis aux conditions spéciales pour une utilisation sûre, mentionnées dans l'annexe de la présente attestation.
 - 11 Cette attestation d'examen de type concerne uniquement la conception, les vérifications et essais de l'appareil de spécifié, conformément à l'annexe VIII la directive 94/9/CE. Des exigences supplémentaires de la directive sont applicables pour la fabrication et la fourniture de l'appareil. Ces dernières ne sont pas couvertes par la présente attestation.
 - 12 Le marquage de l'appareil doit comporter les informations détaillées au point 15.

Fontenay-aux-Roses, le 9 août 2010

1 VOLUNTARY TYPE EXAMINATION CERTIFICATE

- 2 **Equipment** intended for use in potentially explosive atmospheres (Directive 94/9/EC)
 - 3 Type Examination Certificate number
LCIE 10 ATEX 1008 X
 - 4 Equipment
Vibration sensors
Type : EX686B series
 - 5 applicant : PCB Piezotronics
Address : 3425 Walden Avenue
Depew, New York 14043 USA
 - 7 This equipment and any acceptable variation thereto is specified in the schedule to this certificate and the documents therein referred to.
 - 8 LCIE certifies that this equipment has been found to comply with the essential Health and Safety Requirements that relate to the design of equipment, of category 3 electrical or categories 2 and 3 non electrical, which is intended for use in potentially explosive atmospheres, given in Annex II of the Directive 94/9/EC of the European Parliament and Council of 23 March 1994.
- The examination and test results are recorded in confidential report N° 93796/586962.
- 9 Compliance with the Essential Health and Safety Requirements has been assured by reference to :
- EN 60079-0 (2006)
- EN 60079-15 (2005)
 - 10 If the sign X is placed after the certificate number, it indicates that the equipment is subject to special conditions for safe use specified in the schedule to this certificate.
 - 11 This type examination certificate relates only to the design, examination and tests of this specified equipment, in accordance with annex VIII to the directive 94/9/EC. Further requirements of the Directive may apply to the manufacturing process and supply of this equipment. These are not covered by this certificate.
 - 12 The marking of the equipment shall include information as detailed at 15.

Le responsable de certification ATEX
ATEX certification manager



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Société par Actions
au capital de 15 745 981 €
RCS Nanterre B 408 303 171



LCIE



13 ANNEXE

14 ATTESTATION D'EXAMEN DE TYPE VOLONTAIRE

LCIE 10 ATEX 1008 X

15 DESCRIPTION DE L'APPAREIL

Capteur de vibrations
Type : EX686B series

Le capteur de vibrations piézo-électrique utilise un cristal pour convertir une mesure de vibration mécanique en un signal électrique.

Le capteur est en une seule partie, consistant en une enveloppe métallique étanche, contenant un ensemble piézo-cristal et un amplificateur.

Paramètres spécifiques du ou des modes de protection concernés :

12-30VDC ou 24VDC/VAC-240VDC/VAC

Le marquage doit être :

Modèles EX686Bxxxxxx :

PCB Piezotronics Adresse : ...

Type : EX686Bxxxxxx (1)

Numéro de fabrication : ...

Date de fabrication : ...

Ex II 3G

Ex nL IIC T3

LCIE 10 ATEX 1008 X

T amb : -54°C à + 85°C

(1) complété avec le modèle

Modèles EX686B7xxxxxx et

EX686Byyyyyy6 :

PCB Piezotronics Adresse : ...

Type : EX686B7xxxxxx ou EX686Byyyyyy6 (1)

Numéro de fabrication : ...

Année de fabrication : ...

Ex II 3G

Ex nA II T3

LCIE 10 ATEX 1008 X

T amb : -54°C à + 85°C

(1) complété avec le modèle

L'appareil doit également comporter le marquage normalement prévu par les normes de construction qui le concerne.

16 DOCUMENTS DESCRIPTIFS

Dossier technique n° 44999 rév.NR du 16/12/09.

Ce document comprend 8 rubriques (16 pages).

17 CONDITIONS SPECIALES POUR UNE UTILISATION SÛRE

Température ambiante d'utilisation : -54°C à +85°C.

Le matériel ne doit être raccordé qu'à un équipement dont les paramètres électriques sont compatibles aux valeurs mentionnées au paragraphe 15.

13 SCHEDULE

14 VOLUNTARY TYPE EXAMINATION CERTIFICATE

LCIE 10 ATEX 1008 X

15 DESCRIPTION OF EQUIPMENT

Vibrations sensor
Type : EX686B series

The model piezoelectric vibration sensor utilize a crystal to convert a mechanical vibration measurement into an electric signal.

The sensor is 1-piece assembly, consisting of a sealed metal housing, containing the piezo-crystal assembly and the charge amplifier.

Specific parameters of the mode(s) of protection concerned :

12-30VDC or 24VDC/VAC-240VDC/VAC

The marking shall be :

Models EX686Bxxxxxx :

PCB Piezotronics Address : ...

Type : EX686Bxxxxxx (1)

Serial number : ...

Year of construction : ...

Ex II 3G

Ex nL IIC T3

LCIE 10 ATEX 1008 X

T amb : -54°C to + 85°C

(1) completed with the model

Models EX686B7xxxxxx and

EX686Byyyyyy6 :

PCB Piezotronics Address : ...

Type : EX686B7xxxxxx or EX686Byyyyyy6 (1)

Serial number : ...

Year of construction : ...

Ex II 3G

Ex nA II T3

LCIE 10 ATEX 1008 X

T amb : -54°C to + 85°C

(1) completed with the model

The equipment shall also bear the usual marking required by the manufacturing standards applying to such equipment.

16 DESCRIPTIVE DOCUMENTS

Technical file n° 44999 rev.NR dated 12/16/09.

This file includes 8 items (16 pages).

17 SPECIAL CONDITIONS FOR SAFE USE

Operating ambient temperature : -54°C to +85°C

The apparatus must be only connected to an equipment whose electrical parameters are compatible with the values mentioned clause 15.

MEg



LCIE

13 ANNEXE (suite)

14 ATTESTATION D'EXAMEN DE TYPE VOLONTAIRE

LCIE 10 ATEX 1008 X

18 EXIGENCES ESSENTIELLES DE SECURITE ET DE SANTE

Couvertes par les normes listées au point 9.

19 VERIFICATIONS ET ESSAIS INDIVIDUELS

Chaque appareil doit être soumis à un essai de rigidité diélectrique pendant 1 minute sous une tension sinusoïdale de 50 Hz et d'une valeur de 1500V appliquée entre les fils de raccordement et le corps de l'appareil.

20 CONDITIONS DE CERTIFICATION

Les détenteurs d'attestations d'examen de type doivent également satisfaire les exigences de contrôle de production telles que définies au paragraphe 5 de l'annexe VIII de la directive 94/9/CE.

13 SCHEDULE (continued)

14 VOLUNTARY TYPE EXAMINATION CERTIFICATE

LCIE 10 ATEX 1008 X

18 ESSENTIAL HEALTH AND SAFETY REQUIREMENTS

Covered by standards listed at 9.

19 ROUTINE VERIFICATIONS AND TESTS

Each apparatus must be submitted to a dielectric strength test during 1 minute, with a sine-shaped voltage at 50 Hz of 1500 V r.m.s. between the wires of the cable and the body of the apparatus.

20 CONDITIONS OF CERTIFICATION

Holders of type examination certificates are also required to comply with the production control requirements defined in paragraph 5 of annex VIII of directive 94/9/EC.



Certificate of Compliance

Certificate: 2033214

Master Contract: 184981

Project: 80020282

Date Issued: 2019-12-19

Issued To: PCB Piezotronics
3425 Walden Ave
Depew, New York, 14043
United States

Attention: Carrie Termin

The products listed below are eligible to bear the CSA Mark shown with adjacent indicators 'C' and 'US' for Canada and US or with adjacent indicator 'US' for US only or without either indicator for Canada only.



Issued by: *Thong Tong*
Thong Tong

PRODUCTS

CLASS - C225803 - PROCESS CONTROL EQUIPMENT - Intrinsically Safe and Non Incendive Systems - For Hazardous Locations

CLASS - C225883 - PROCESS CONTROL EQUIPMENT-Intrinsically Safe and Non-Incendive Systems-For Hazardous Locations-Certified to U.S. Standards

Ex nL IIC T3:

AEx nA IIC T3:

Class I, Div. 2, Groups A, B, C, D:

Models EX686X0x Vibration Sensors, input rated 12-30 Vdc max, 1 mA consumption, 100 mA max. flow-through; non-incendive with entity parameters of: U_i (V max) = 30V, I_i (I max) = 100mA, P_i (Pmax) = 1W, C_i = 0, L_i = 28 uH; when installed per installation Dwg 39483; Temp Code T3 @ Max Ambient 85 Deg C.

Models EX686X1y and EX686X6y Vibration Sensors, input rated 12-30 Vdc max, 1 mA consumption, 100 mA max. flow-through; non-incendive with entity parameters of: U_i (V max) = 30V, I_i (I max) = 100mA, P_i (Pmax)



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= 1W, Ci = 61 nF, Li = 333 μ H; when installed per installation Dwg 39483; Temp Code T3 @ Max Ambient 85 Deg C.

Notes:

1. For Canadian Installations, sensor case must be bonded to ground according to Section 18 of the CEC, Part 1.
2. For US Installations, sensor case must be bonded to ground according to Articles 501 and 505 of the NEC.
3. Letter X following product identifier number EX686 may be a capital letter from B to Z denoting Model revision level for minor revisions restricted to changes of values of capacitors and resistors within the approval limits specified on control drawing 39481 page 1 and 2. The "x" or "y" in the model code may be a number from 0 thru 9 which denotes variations in frequency response, sensitivity, and mounting configuration of the sensors.
4. An alphanumeric code (-XXXXX) following the Model Number indicates cable length and termination. Cable length not to exceed 304.5m (999ft).

CLASS 2258 02 - PROCESS CONTROL EQUIPMENT - For Hazardous Locations

CLASS 2258 82 - PROCESS CONTROL EQUIPMENT - For Hazardous Locations - CERTIFIED TO U.S. STANDARDS

4.

Ex nA IICT3:

AEx nA IIC T3:

Class I, Div. 2, Groups A, B, C, D:

Models EX686X7x Vibration Sensors, input rated 24-240 Vdc, 1 mA consumption, 500 mA max. flow-through; 24-240 Vac, 50/60 Hz, 1 mA consumption, 500 mA max. flow-through; suitable for use in Class I, Div. 2 or Class I, Zone 2 locations, when installed per installation Dwg 39486; Temp Code T3 @ Max Ambient 85 Deg C.

Models EX686Xyyyyyy6 Vibration Sensors, input rated 24-240 Vdc, 1 mA consumption, 500 mA max. flow-through; 24-240 Vac, 50/60 Hz, 1 mA consumption, 500 mA max. flow-through; suitable for use in Class I, Div. 2 or Class I, Zone 2 locations, when installed per installation Dwg 39486; Temp Code T3 @ Max Ambient 85 Deg C.

Notes:

1. Sensor must be installed in a suitable enclosure, acceptable to the local inspection authority having jurisdiction.
2. Letter X following product identifier number EX686 may be a capital letter from B to Z denoting Model revision level for minor revisions restricted to changes of values of capacitors and resistors within the approval limits specified on control drawing 39481 page 1 and 2. The "x" in the model code may be a number from 0 thru 9 which denotes variations in frequency response, sensitivity, and mounting configuration of the sensors.



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Project: 80020282

Master Contract: 184981
Date Issued: 2019-12-19

3. An alphanumeric code (-XXXXX) following the Model Number indicates cable length and termination. Cable length not to exceed 304.5m (999ft).
4. The “yyyyy” in the model code may be a number from 0 thru 9 which denotes variations in frequency response, sensitivity, and mounting configuration of the sensors.

APPLICABLE REQUIREMENTS

CAN/CSA-C22.2 No. 0-M91	- General Requirements – Canadian Electrical Code, Part II
C22.2 No. 142-M1987	- Process Control Equipment
C22.2 No. 213-M1987	- Non-Incendive Electrical Equipment for Use in Class I, Division 2 Hazardous Locations
UL 916 (3 rd Ed.)	- Energy Management Equipment
UL 1604 (3 rd Ed.)	- Electrical Equipment for Use in Class I and II, Division 2; Class III Hazardous (Classified) Locations
ANSI/ISA 12.12.01-2007	- Nonincendive Electrical Equipment for Use in Class I and II, Division 2 and Class III, Divisions 1 and 2 Hazardous (Classified) Locations
CAN/CSA-E60079-15:02	- Electrical apparatus for explosive gas atmospheres - Part 15: Type of Protection "n"
ANSI/UL 60079-15:02	- Electrical apparatus for Explosive Gas Atmospheres - Part 15: Type of Protection “n”

MARKINGS

The manufacturer is required to apply the following markings:

- Products shall be marked with the markings specified by the particular product standard.
- Products certified for Canada shall have all Caution and Warning markings in both English and French.

Additional bilingual markings not covered by the product standard(s) may be required by the Authorities Having Jurisdiction. It is the responsibility of the manufacturer to provide and apply these additional markings, where applicable, in accordance with the requirements of those authorities.

The products listed are eligible to bear the CSA Mark shown with adjacent indicators 'C' and 'US' for Canada and US (indicating that products have been manufactured to the requirements of both Canadian and U.S. Standards) or with adjacent indicator 'US' for US only or without either indicator for Canada only.

Markings are etched directly into the Sensor enclosure body. The following marking details appear:

Div. 2 Non-Incendive models

- CSA Monogram with C US indicator.



Certificate: 2033214
Project: 80020282

Master Contract: 184981
Date Issued: 2019-12-19

- Submittor Identification
- Model Number
- Serial Number, Date Code or Month and Year of Manufacture
- Electrical Rating
- Hazardous Location Designation (ie Ex nL IICT4, AEx nA IICT4, Class I, Div. 2, Groups A, B, C and D)
(In addition to these required markings, the following optional markings may also appear: Class I, Zone 2, Group IIC, T4)
- Certificate # reference (ie. 2008 2033214)
- "WARNING – EXPLOSION HAZARD. DO NOT CONNECT OR DISCONNECT WHEN ENERGIZED." or equivalent.
- "AVERTISSEMENT – RISQUE D'EXPLOSION. NE PAS BRANCHER NI DÉBRANCHER SOUS TENSION." or equivalent.

Div. 2 Non-arcing models (.....X7x)

- CSA Monogram with C US indicator.
- Submittor Identification
- Model Number
- Serial Number, Date Code or Month and Year of Manufacture
- Electrical Rating
- Hazardous Location Designation (ie Ex nA IIC T3, AExnA IICT3, Class I, Div. 2, Groups A, B, C and D)
(In addition to these required markings, the following optional markings may also appear: Class I, Zone 2, Group IIC, T3)
- Certificate # reference (ie. 2008 2033214 X)
- "WARNING – EXPLOSION HAZARD. DO NOT CONNECT OR DISCONNECT WHEN ENERGIZED." or equivalent.
- "AVERTISSEMENT – RISQUE D'EXPLOSION. NE PAS BRANCHER NI DÉBRANCHER SOUS TENSION." or equivalent.

ALTERATIONS

1. Markings as above appear.
2. Internal wiring is rated for temperatures of 200 Deg. C.



Supplement to Certificate of Compliance

Certificate: 2033214

Master Contract: 184981

*The products listed, including the latest revision described below,
are eligible to be marked in accordance with the referenced Certificate.*

Product Certification History

Project	Date	Description
80020282	2019-12-19	Update to CSA report 2033214 to change Model EX686B to EX686X to allow minor modifications.
0002033214	2008-09-25	Model EX686B Series Vibration sensors for Class I, Div. 2, and Zone 2 hazardous locations - North America

EU Declaration of Conformity PS060

In Accordance with ISO/IEC 17050

Manufacturer:

PCB Piezotronics, Inc.
 3425 Walden Avenue
 Depew, New York 14043
 USA

Authorized European Representative:

PCB Piezotronics GmbH
 Gut Gansbroich 1
 41836 Hückelhoven
 Germany

Certifies that type of equipment: ICP® Industrial Vibration Sensor(s)

Whose Product Models Include: EX(XX)602yzzz/aaa, EX(XX)603yzzz/aaa, EX(XX)606yzzzlaaa, EX(XX)607yzzz/aaa, EX(XX)608yzzz/aaaSeries

Note: "xx" is a place holder for two numbers.

For example: EX602D01Industrial Vibration Sensor
 These letters and numbers are included in the model numbers of the series.
 For details see the related data sheets.

This declaration is applicable to all ICP® Industrial Vibration Sensor(s) of the above series which have the ATEX mark on their data sheets and where those data sheets refer to this declaration of conformity. The data sheets for all model numbers referenced above, which include the ATEX mark on such data sheets and refer to this Declaration of Conformity are hereby incorporated by reference into this Declaration.

Conform to the following EU
 Directive(s) when installed per
 product documentation:

2014/30/EU
 2014/34/EU
 2011/65/EU w/2015/863/EU

EMC Directive
 ATEX Directive
 RoHS Directive

Harmonized Standards to which Conformity is Declared:

Harmonized Standards	EN 61326-1:2013	Electrical Equipment for Measurement, Control and Laboratory Use- EMC requirements - Part 1: General requirements
	EN 61326-2-3: 2013	Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 2-3: Particular requirements - Test configuration, operational conditions and performance criteria for transducers with integrated or remote signal conditioning
	EN 61010-1:2010 EN 61010-1:2010/A1:2019/AC:2019-04 EN 61010-1:2010/A1:2019	Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use - Part 1: General Requirements
	EN IEC 60079-0:2018+A11:2024	Explosive Atmosphere - Part 0: Equipment - General requirements
	EN IEC 60079-7:2015+A1:2018	Explosive atmospheres - Part 7: Equipment protection by increased safety "e"
	EN 60079-11 2012	Explosive atmospheres - Part 11: Equipment protection by intrinsic safety "i"
	EN IEC 60079-15:2019	Explosive atmospheres - Part 15: Equipment protection by type of protection "n"
	EN IEC 63000:2018	Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances(IEC 63000:2018)
Emissions Test Standards	EN 55011:2016, EN 55011:2016/A1:2017 EN 55011:2016/A11:2020	Industrial, scientific and medical (ISM) radio frequency equipment-Electromagnetic disturbance characteristics- Limits and methods of Measurement Class B

Other Standards Applied (non-OJEU) Immunity Test Standards	EN 61000-4-2:2009	Electromagnetic compatibility (EMC)–Part 4–2: Testing and measuring techniques– Electrostatic discharge immunity test
	EN 61000-4-3:2006+ A2:2010	Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test
	EN 61000-4-4:2012	Electromagnetic compatibility (EMC) - Part 4-4: Testing and measurement techniques - Electrical fast transient/burst immunity test
	EN 61000-4-5:2014	Electromagnetic compatibility (EMC) - Part 4-5: Testing and measurement techniques - Surge immunity test
	EN 61000-4-6:2014	Electromagnetic compatibility (EMC) - Part 4-6: Testing and measurement techniques - Immunity to conducted disturbances, induced by radio-frequency fields
	EN 61000-4-8:2010	Electromagnetic compatibility (EMC) – Part 4-8: Testing and measurement techniques – Power frequency magnetic field immunity test
Test Reports	EMC Reports Safety Reports	GM29028c, GM29030c, GM29032c, GM29045c GM29029s, GM29031s, GM29033s, GM29046s
EC Type Examination	ATEX Certification EN IEC 60079-0:2018+A11:2024 EN 60079-11:2012	ETL25ATEX0596X Ex ia IIC T4, II 1G
Voluntary Certification	Voluntary Type Examination EN IEC 60079-0:2018+A11:2024 EN IEC 60079-7:2015+A1:2018 EN IEC 60079-15:2019	ETL25ATEX0595X Ex ec nC IIC T4 Gc
Other International Certifications	IECEX Certification IEC 60079-0:2017 (Edition:7.0) IEC 60079-7:2017 (Edition:5.1) IEC 60079-11:2011(Edition:6.0) IEC 60079-15:2017 (Edition:5.0)	IECEX ETL 25.0046X Ex ia IIC T4 Ga Ex ec nC IIC T4 Gc
Notified Body Name		Intertek Testing Services NA Ltd
Notified Body's Address		Intertek Testing Services NA Ltd 14920-135 Avenue Edmonton, AB, T5V 1R9, Canada Tel.: +1 780-440-4455

I, the undersigned, hereby declare that the equipment specified above conforms to the above Directive(s) Standard(s)

Place: Depew, NY **Date:** 11/24/2025

Signature:



Name: Lance Pellens

Title: Director – Quality Assurance

UK Declaration of Conformity PS107UK

In Accordance with ISO/IEC 17050

Manufacturer:
PCB Piezotronics, Inc.
3425 Walden Avenue
Depew, New York 14043
USA

Authorized UK Representative:
PCB Piezotronics Ltd
Business and Technology Center
Bessemer Drive
Stevenage
Hertfordshire, SG1 2DX
United Kingdom



Certifies that type of equipment: ICP® Industrial Vibration Sensor(s)

Whose Product Models Include: EX(XX)602yzzz/aaa, EX(XX)603yzzz/aaa, EX(XX)606yzzzlaaa,
EX(XX)607yzzz/aaa, EX(XX)608yzzz/aaa Series

Note: "xx" is a place holder for two numbers.

For example: EX602D01Industrial Vibration Sensor
These letters and numbers are included in the model numbers of the series.
For details see the related data sheets.

This declaration is applicable to all ICP® Industrial Vibration Sensor(s) of the above series which have the UKCA mark on their data sheets and where those data sheets refer to this declaration of conformity. The data sheets for all model numbers referenced above, which include the UKCA mark on such data sheets and refer to this Declaration of Conformity are hereby incorporated by reference into this Declaration.

Conform to the following UK Statutory Requirements when installed per product documentation:

Electromagnetic Compatibility Regulations 2016 (SI 2016 No. 1091) Electrical Equipment (Safety) Regulations 2016
The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 (SI2012No3032 as Amended by SI2019 No696)

Designated Standards to which Conformity is Declared:

Designated Standards	BS EN 61326-1:2013 BS EN 61326-2-3:2013 BS EN 61010-1:2010 BS EN 61010-1:2010/A1:2019/AC:2019-04 BS EN 61010-1:2010/A1:2019 BS EN IEC 63000:2018	Electrical Equipment for Measurement, Control and Laboratory Use- EMC requirements - Part 1: General requirements Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 2-3: Particular requirements - Test configuration, operational conditions and performance criteria for transducers with integrated or remote signal conditioning Safety requirements for electrical equipment for measurement, control, and laboratory use - Part 1: General requirements Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances (IEC 63000:2018)
Emissions Test Standards	BS EN 55011:2016, BS EN 55011:2016/A1:2017 BS EN 55011:2016/A11:2020	Industrial, scientific and medical (ISM) radio frequency equipment-Electromagnetic disturbance characteristics- Limits and methods of Measurement Class B

Other Standards Applied (non-OJEU) Immunity Test Standards	BS EN 61000-4-2:2009	Electromagnetic compatibility (EMC)–Part 4–2: Testing and measuring techniques– Electrostatic discharge immunity test
	BS EN 61000-4-3:2006+A2:2010	Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test
	BS EN 61000-4-4:2012	Electromagnetic compatibility (EMC) - Part 4-4: Testing and measurement techniques - Electrical fast transient/burst immunity test
	BS EN 61000-4-5:2014	Electromagnetic compatibility (EMC) - Part 4-5: Testing and measurement techniques - Surge immunity test
	BS EN 61000-4-6:2014	Electromagnetic compatibility (EMC) - Part 4-6: Testing and measurement techniques - Immunity to conducted disturbances, induced by radio-frequency fields
	BS EN 61000-4-8:2010	Electromagnetic compatibility (EMC) – Part 4-8: Testing and measurement techniques – Power frequency magnetic field immunity test
Test Reports	EMC Reports Safety Reports	GM29028c, GM29030c, GM29034c, GM29045c GM29029s, GM29031s, GM29035s, GM29046s

I, the undersigned, hereby declare that the equipment specified above conforms to the above Directive(s) Standard(s)

Place: Depew, NY **Date:** 11/24/2025

Signature:



Name: Lance Pellens

Title: Director – Quality Assurance